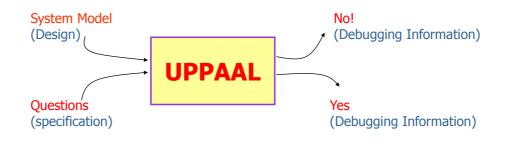
Modeling & Analysis of Timed Systems

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CUGS May 7-8, 2012

Main goal of this course

What's inside the tools: UPPAAL & TIMES (and also some recent work on multicore timing analysis if time allows) 1



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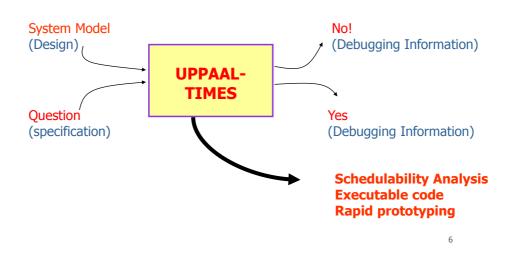
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UPPAAL: www.uppaal.com

- Developed jointly by
 - Uppsala university, Sweden
 - Aalorg university, Denmark
- UPPsala + AALborg = UPPAAL
 - SWEDEN + DENMARK = SWEDEN
 - SWEDEN + DENMARK = DENMARK

- A branch of UPPAAL, developed at Uppsala
- TIMES = a Tool for Modeling and Implemenation of Embedded Systems





OUTLINE

- A Brief Introduction
 - Motivation ... what are the problems to solve
 - CTL, LTL and basic model-checking algorithms
- Timed Systems
 - Timed automata, TCTL and verification problems
 - UPPAAL tutorial: data stuctures & algorithms
 - TIMES: schedulability analysis using timed automata
- Recent Work
 - The multicore timing analysis problems
 - Some solutions: WCET analysis and multiprocessor scheduling

Main references (papers)

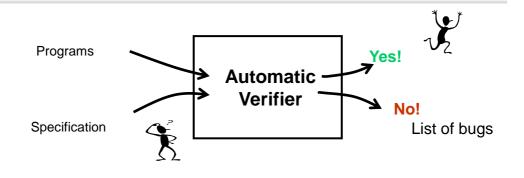
- Temporal Logics (CTL,LTL)
 Automatic Verification of Finite State Concurrent Systems Using Temporal Logic Specifications: A Practical Approach. Edmund M. Clarke, E. Allen Emerson, A. Prasad Sistla, POPL 1983: 117-126, also as "Automatic Verification of Finite-State Concurrent Systems Using Temporal Logic Specifications. ACM Trans. Program, Lang. Syst. 8(2): 244-263 (1986) "
 - An Automata-Theoretic Approach to Automatic Program Verification, Moshe Y. Vardi, Pierre Wolper: LICS 1986: 332-344. Also as " Reasoning About Infinite Computations. Inf. Comput. 115(1): 1-37 (1994)"
- Timed Systems (Timed Automata, TCTL)
 - A Theory of Timed Automata. Rajeev Alur, David L. Dill. Theor. Comput. Sci. 126(2): 183-235 (1994)"
 - Symbolic Model Checking for Real-Time Systems, Thomas A. Henzinger, Xavier Nicollin, Joseph Sifakis, and Sergio Yovine. Information and Computation 111:193-244, 1994.
 - UPPAAL in a Nutshell. Kim Guldstrand Larsen, Paul Pettersson, Wang Yi. STTT 1(1-2): 134-152 (1997)
 - **Timed Automata Semantics, Algorithms and Tools**, a tutorial on timed automata Johan Bengtsson and Wang Yi: (a book chapter in Rozenberg et al, 2004, LNCS). **On-line help of UPPAAL**: www.uppaal.com

Main references (books)

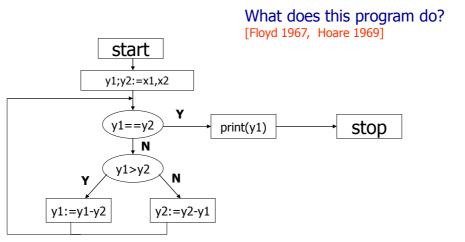
- Edmund M. Clarke, Orna Grumberg and Doron A. Peled, Model Checking
- G.J. Holzmann, Prentice Hall 1991, Design and Validation of Computer Protocols (newer book: The SPIN MODEL CHECKER Primer and Reference Manual, 2003)
- Joost-Pieter Katoen and Christel Baier, Concepts, Algorithms, and Tools for Model Checking (MIT press)

Lecture 1 Motivation and some historical remarks

Dream: Program verifier



The dream started 40 years ago in 1960's aiming at "bug-free software"



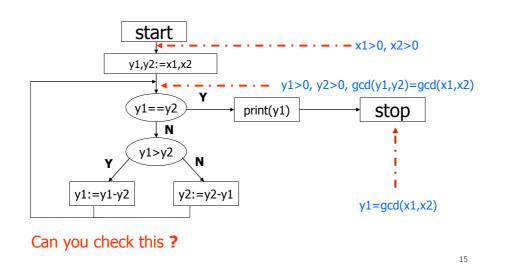
It computes the Greatest Common Divisor (gcd) of x1 and x2 [Floyd 67]

Specification (partial correctness)

Hoare logic: {P} program {Q} [Floyd 1967, Hoare 1969]

- Assume, initially (pre-condition)
 - x1>0, x2>0
- After each iteration of the loop (invariant)
 - y1>0, y2>0, gcd(x1,x2) = gcd(y1,y2)
- When done (post-condition)
 - y1=gcd(x1,x2)

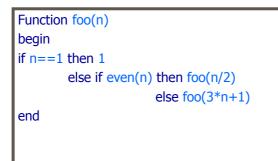
What does this program do?



Yes, you may prove it manually by induction on the number of iterations. Question: can you automate the proof ?

Software verification (now, a hot topic)

One more example (Total correctness)



Does this program terminate for any n? (WCET?)

Reality: 10 years later (1980's)

- The majority of programs are never proven correct! what went wrong?
 - Difficult to find and prove invariants: partial correctness
 - Difficult/impossible to prove termination: total correctness
 - Difficult to write complete specifications: what I really want?
- What to do?
 - Start another research program! In 20 years, the problems will be solved, hopefully

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History: Model-checking invented in 70's/80s

[Pnueli 77, Clarke et al 83, POPL83, Sifakis et al 82]

- Restrict attention to finite-state programs
 - Control skeleton + boolean (finite-domain) variables
 - Found in hardware design, communication protocols, process control
- Temporal logic specification of e.g., synchronization pattern
 - There are algorithms to check that MODEL of program satisfies: SPEC
 - e.g. Alternating Bit Protocol skeleton, around 140 states, 1984
- BDD-based symbolic technique [Bryant 86]
 - SMV 1990 Clarke, McMillan et al, state-space 10²⁰
 - Now powerful tools used in processor design
- On-the-fly enumerative technique [Holzman 89]
 - SPIN, COSPAN, CAESAR, KRONOS, IF/BIP, UPPAAL etc
- SAT-based techniques [Clarke et al, McMillan, ...]

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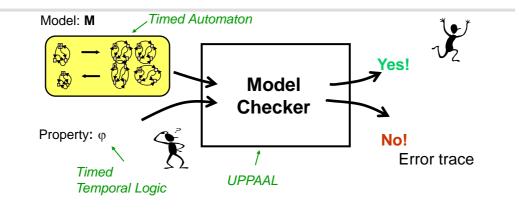
History: Model checking for real time systems, started in the 80s/90s

- Extension of model checking to consider time quantities
 Models, specfications, and algorithms can be extended
- Timed automata, timed process algebras

[Alur&Dill 1990]

- Tools
 - KRONOS, Hytech, 1993-1995, IF 2000's
 - TAB 1993, UPPAAL 1995, TIMES 2002

Model Checking



Problems that can be addresed by Model Checking

Checking correctness of

- Communication protocols
- Distributed Algorithms
- Controllers
- Hardware circuits
- Parallel and distributed software
- Embedded and real-time systems and software
- e.g., Absence of race conditions, proper synchronization,

Model checking is the appropriate technique when there are many different scenarios of interaction between components in a system

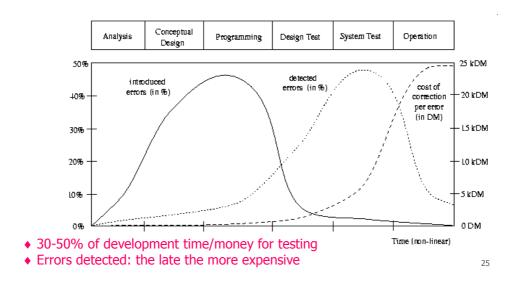
Why testing not good enough

- **Testing/simulation**: coverage problems, difficult to deal with non-determinism and concurrent computation
- Formal verification/Model-Checking (= exhaustive testing of software and hardware design) provides 100% coverage

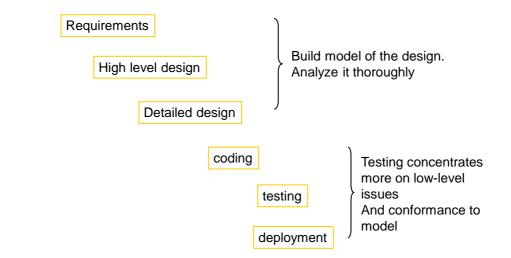
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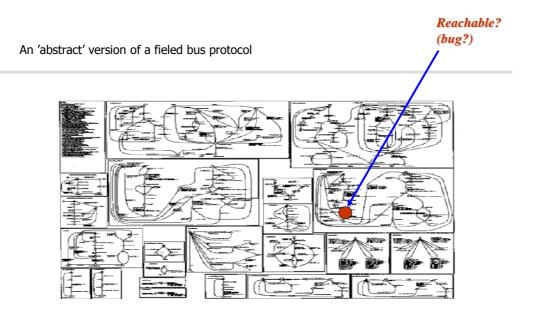
Model-Checking may complement testing to find (design) Bugs as early as possible

Introducing, Detecting and Correcting errors



Motivation: Model Verification





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Model-Checking in a Nutshell

EXAMPLE: Petersson's algorithm

turn, flag1, flag2: shared variable

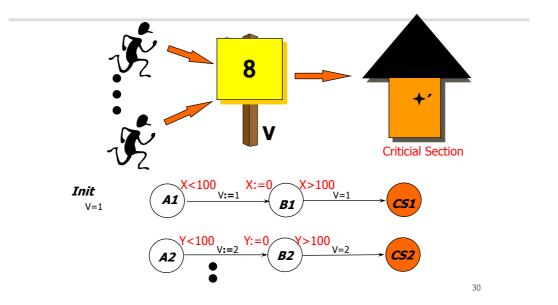
- Process 1
- loop
- flag1:=1; turn:=2
- while (flag2 & turn=2) wait
- <u>CS1</u>
- flag1:=0
- end loop

- Process 2
- loop
- flag2:=1; turn:=1
- while (flag1 & turn=1) wait
- <u>CS2</u>
- flag2:=0
- end loop

Question: can both run in CS simultaneusly ?

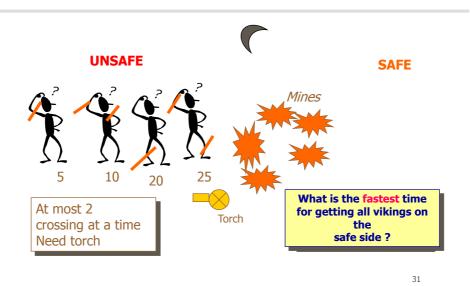
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Example: Fischer's Protocol

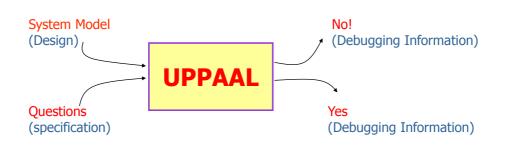


Example: the Vikings Problem

Real time scheduling



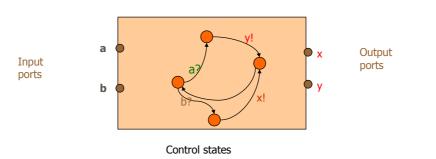
UPPAAL A model checker for real-time systems



MODELING

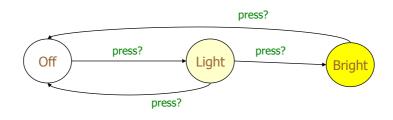
How to construct Model?

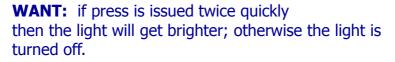
Program as State Machine!



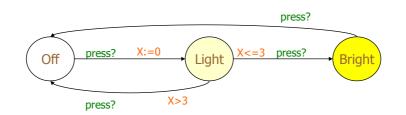
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A Light Controller



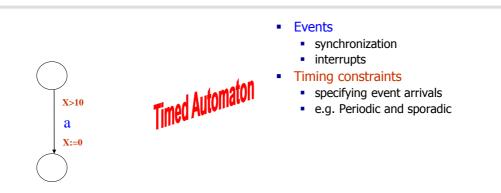


A Light Controller (with timer)



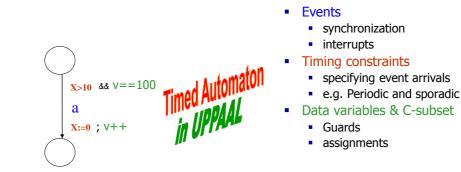
Solution: Add real-valued clock x

Modeling Real Time Systems

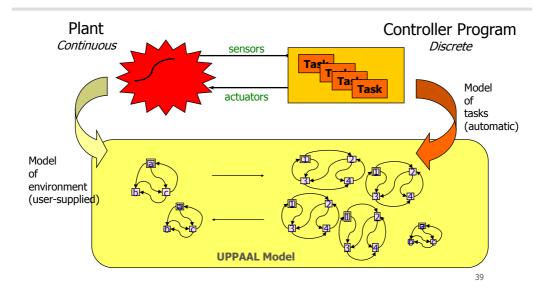


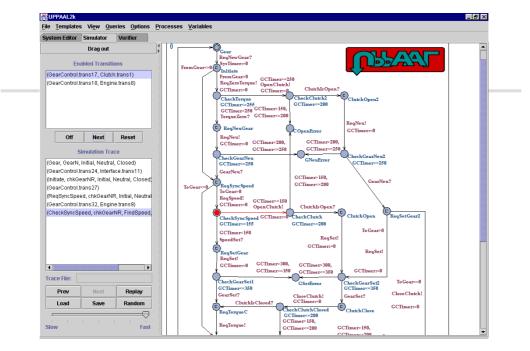
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Modeling Real Time Systems



Construction of Models: Concurrency





SPECIFICATION

How to ask questions: Specs ?

Specification=Requirement, Lamport 1977

- Safety
 - Something (bad) will not happen
- Liveness
 - Something (good) must happen

Specification=Requirement [Lamport 1977]

- Safety
 - Something (bad) will not happen
- Liveness
 - Something (good) must happen
- Realizability (for systems with limited resources)
 - Schedulability, enough resources?

Specification: Examples

- Safety
 - AG ¬(P1.CS1 & P2.CS2)
 - AG (m< 100)
 - EF (5<6)

Eventually

Leads to

- construct the whole state space
- Report deadlocks etc.
- EF (viking1.safe & viking2.safe & viking3.safe & viking4.safe)
- AG (time>60 imply viking4.safe)

Liveness

- AF (m>100)
- AG (P1.try imply AF P1.CS1)

Possibly in Future

Always Globally

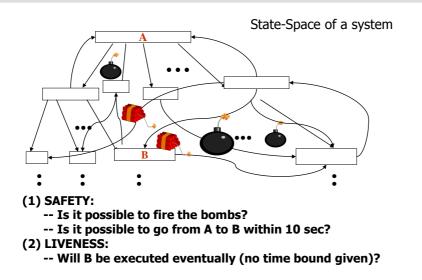


Model meets Specs ?

(Formal) Verification

- Semantics of a system
 - = all states + state transitions (all possible executions)
- Verification
 - = state space exploration + examination

Verificatioin = Searching



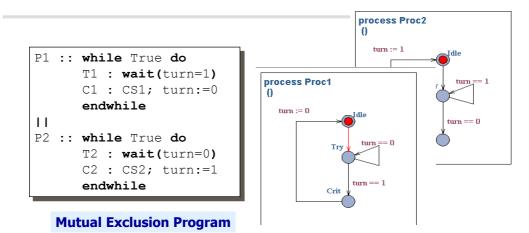
Approaches to Verification

- Manual: Proof systems, paper and pen
 - Find invariants (difficult !)
 - Induction: Assume nth-state OK, check (n+1)th OK
 - Boring ⊗ (more fun with programming)
- Semi-automatic: Theorem proving
 - Use theorem provers to prove the induction step
 - e.g. PVS, HOL, Coq
 - Require too much expertise ⊗
- Automatic: Model-Checking ©
 - State-Space Exploration and Examination
 - e.g. SPIN, SMV, UPPAAL

Two basic verification algorithms

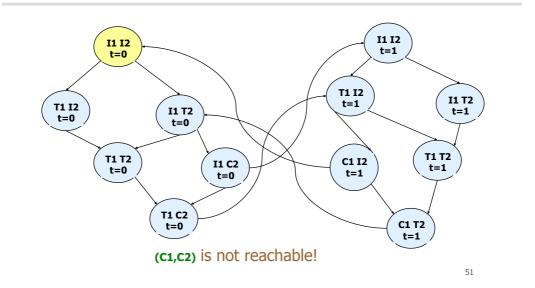
- Reachability analysis
 - Checking safety properties
- Loop detection
 - Checking liveness properties

Modelling in UPPAAL: example



Is it possible that P1 and P2 run C1 and C2 simultaneously?

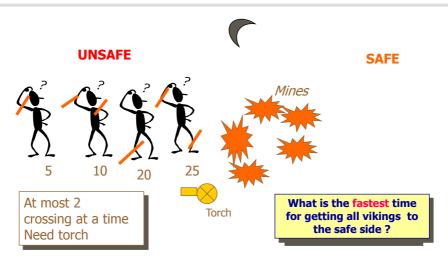
Verification: example



UPPAAL Demo

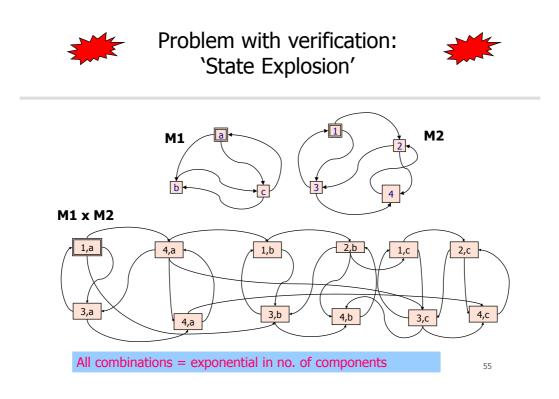
Example: the Vikings Problem

Real time scheduling



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This sounds too good! What's the problem?



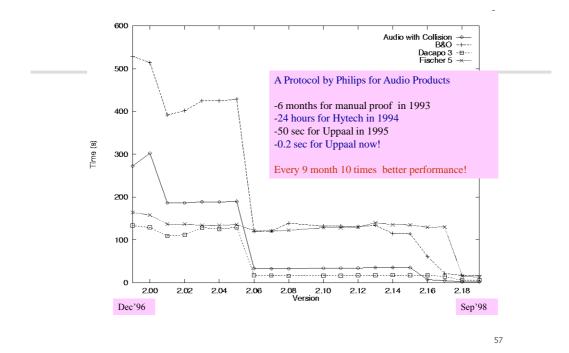
EXAMPLE

13 components and each with 1 clock & 10 states

of states = 10,000,000,000 = 10,000 G Each needs (10 * 10)* 4Bytes = 400 Bytes

Worst case memory usage >> 4,000,000GB





The dream goes on

 Model Checking, a useful and applicable technique as compiler theory

End of introduction