

# Bounded Model Generation for Isabelle/HOL

## *Using a SAT Solver*

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# Isabelle

*Isabelle* is a generic proof assistant:

- Highly flexible
- Interactive
- Automatic proof procedures
- Advanced user interface
- Readable proofs
- Large theories of formal mathematics



# Bounded Model Generation

Theorem proving: from formulae to proofs

Bounded model generation: *from formulae to models*

Applications:

- *Finding counterexamples to false conjectures*
- Showing the consistency of a specification
- Solving open mathematical problems
- Guiding resolution-based provers



# Isabelle/HOL

**HOL**: higher-order logic based on Church's simple theory of types (1940)

Simply-typed  $\lambda$ -calculus:

- Types:  $\sigma ::= \mathbb{B} \mid \alpha \mid \sigma \rightarrow \sigma$
- Terms:  $t_\sigma ::= x_\sigma \mid (t_{\sigma' \rightarrow \sigma} t_{\sigma'})_\sigma \mid (\lambda x_{\sigma_1}. t_{\sigma_2})_{\sigma_1 \rightarrow \sigma_2}$

Two logical constants:

- $\implies_{\mathbb{B} \rightarrow \mathbb{B} \rightarrow \mathbb{B}}, =_{\sigma \rightarrow \sigma \rightarrow \mathbb{B}}$



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Other constants, e.g.

$\text{True} \mid \text{False} \mid \neg \mid \wedge \mid \vee \mid \forall \mid \exists \mid \exists!$

are definable.



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Set-theoretic semantics:

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An *environment*  $D$  assigns to each type variable  $\alpha$  a non-empty set  $D_\alpha$ .

Semantics of types:

- $D(\mathbb{B}) = \{\top, \perp\}$
- $D(\alpha) = D_\alpha$
- $D(\sigma_1 \rightarrow \sigma_2) = D(\sigma_2)^{D(\sigma_1)}$



# The Semantics of HOL (2)

A *variable assignment*  $A$  maps each variable  $x_\sigma$  to an element  $A(x_\sigma)$  in  $D(\sigma)$ .

Semantics of terms:

- $\llbracket x_\sigma \rrbracket_D^A = A(x_\sigma)$
- $\llbracket (t_{\sigma' \rightarrow \sigma} t_{\sigma'})_\sigma \rrbracket_D^A = \llbracket t_{\sigma' \rightarrow \sigma} \rrbracket_D^A (\llbracket t_{\sigma'} \rrbracket_D^A)$
- $\llbracket (\lambda x_{\sigma_1}. t_{\sigma_2})_{\sigma_1 \rightarrow \sigma_2} \rrbracket_D^A$  is the function that sends each  $d$  in  $D(\sigma_1)$  to  $\llbracket t_{\sigma_2} \rrbracket_D^{A[x_{\sigma_1} \mapsto d]}$
- $\Longrightarrow_{\mathbb{B} \rightarrow \mathbb{B} \rightarrow \mathbb{B}}, =_{\sigma \rightarrow \sigma \rightarrow \mathbb{B}}$ : implication, equality

Hence the semantics of a term is an element of the set denoted by the term's type.





# Overview

*Input:* HOL formula  $\phi$

*Output:* either a model for  $\phi$ , or “no model found”



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*Input:* HOL formula  $\phi$

1. Fix a finite environment  $D$ .
2. Translate  $\phi$  into a Boolean formula that is satisfiable iff  $\llbracket \phi \rrbracket_D^A = \top$  for some variable assignment  $A$ .
3. Use a SAT solver to search for a satisfying assignment.
4. If a satisfying assignment was found, compute from it the variable assignment  $A$ . Otherwise repeat for a larger environment.

*Output:* either a model for  $\phi$ , or “no model found”



# Fixing a Finite Environment

Fix a positive integer for every type variable that occurs in the typing of  $\phi$ .

Every type then has a finite size:

- $|\mathbb{B}| = 2$
- $|\alpha|$  is given by the environment
- $|\sigma_1 \rightarrow \sigma_2| = |\sigma_2|^{|\sigma_1|}$

Finite model generation is a generalization of satisfiability checking, where the search tree is not necessarily binary.

# Translation into a Boolean Formula

Boolean formulae:

$$\varphi ::= \text{True} \mid \text{False} \mid p \mid \neg\varphi \mid \varphi \vee \varphi \mid \varphi \wedge \varphi$$

Idea: Translate a HOL term  $t_\sigma$  into a *tree of Boolean formulae*. The interpretation of the Boolean variables in the tree determines the interpretation of  $t_\sigma$ .



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- $\text{create}(\mathbb{B}) = [p_1, p_2]$
- $\text{create}(\alpha) = [p_1, \dots, p_{|\alpha|}]$
- $\text{create}(\sigma_1 \rightarrow \sigma_2) = [\underbrace{\text{create}(\sigma_2), \dots, \text{create}(\sigma_2)}_{|\sigma_1|}]$



# Translation into a Boolean Formula (2)

- $\text{treemap}(f, t)$  applies  $f$  to every node of the tree  $t$
- $\text{merge}(f, t_1, t_2)$  applies  $f$  to corresponding nodes of  $t_1$  and  $t_2$
- $\text{apply}([t], [\varphi]) = \text{treemap}((\lambda\varphi'.\varphi' \wedge \varphi), t)$
- $\text{apply}([t_1, t_2, \dots, t_n], [\varphi_1, \varphi_2, \dots, \varphi_n]) =$   
 $\text{merge}(\vee, \text{apply}([t_1], [\varphi_1]), \text{apply}([t_2, \dots, t_n], [\varphi_2, \dots, \varphi_n]))$
- $\text{enum}([\varphi_1, \dots, \varphi_n]) = [\varphi_1, \dots, \varphi_n]$
- $\text{enum}([t_1, \dots, t_n]) =$   
 $\text{map}(\text{all}, \text{pick}([\text{enum}(t_1), \dots, \text{enum}(t_n)]))$

# Translation into a Boolean Formula (3)

- $\mathcal{T}_D^B(x_\sigma) = \begin{cases} B(x_\sigma) & \text{if } x_\sigma \in \text{dom } B \\ \text{create}(\sigma) & \text{otherwise} \end{cases}$
- $\mathcal{T}_D^B((t_{\sigma' \rightarrow \sigma} t'_{\sigma'})_\sigma) = \text{apply}(\mathcal{T}_D^B(t_{\sigma' \rightarrow \sigma}), \text{enum}(\mathcal{T}_D^B(t'_{\sigma'})))$
- $\mathcal{T}_D^B((\lambda x_{\sigma_1}. t_{\sigma_2})_{\sigma_1 \rightarrow \sigma_2}) =$   
 $[\mathcal{T}_D^{B[x_{\sigma_1} \mapsto d_1]}(t_{\sigma_2}), \dots, \mathcal{T}_D^{B[x_{\sigma_1} \mapsto d_{|\sigma_1|}]}(t_{\sigma_2})],$   
where  $[d_1, \dots, d_{|\sigma_1|}] = \text{consts}(\sigma_1)$

# Example Translation

$$S : \alpha \rightarrow \beta, T : \alpha, |\alpha| = 2, |\beta| = 3$$



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$$S = [[s_1^1, s_2^1, s_3^1], [s_1^2, s_2^2, s_3^2]]$$

$$T = [t_1, t_2]$$

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$$S = [[s_1^1, s_2^1, s_3^1], [s_1^2, s_2^2, s_3^2]]$$

$$T = [t_1, t_2]$$

$$(ST) = [s_1^1 \wedge t_1, s_2^1 \wedge t_1, s_3^1 \wedge t_1]$$

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$$S : \alpha \rightarrow \beta, T : \alpha, |\alpha| = 2, |\beta| = 3$$

$$S = [[s_1^1, s_2^1, s_3^1], [s_1^2, s_2^2, s_3^2]]$$

$$T = [t_1, t_2]$$

$$(S T) = [s_1^1 \wedge t_1 \vee s_1^2 \wedge t_2, s_2^1 \wedge t_1 \vee s_2^2 \wedge t_2, s_3^1 \wedge t_1 \vee s_3^2 \wedge t_2]$$

# The SAT Solver

Several *external* SAT solvers (zChaff, BerkMin, Jerusat, ...) are supported.

- Efficiency
- Advances in SAT solver technology are “for free”

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Simple *internal* solvers are available as well.

- Easy installation
- Compatibility
- Fast enough for small examples

# Some Extensions

*Sets* are interpreted as characteristic functions.

- $\sigma \text{ set} \cong \sigma \rightarrow \mathbb{B}$

- $x \in P \cong P x$

- $\{x. P x\} \cong P$

Non-recursive *datatypes* can be interpreted in a finite model.

- $(\alpha_1, \dots, \alpha_n)\sigma ::= C_1 \sigma_1^1 \dots \sigma_{m_1}^1 \mid \dots \mid C_k \sigma_1^k \dots \sigma_{m_k}^k$

- $|(\alpha_1, \dots, \alpha_n)\sigma| = \sum_{i=1}^k \prod_{j=1}^{m_i} |\sigma_j^i|$

- Examples: *option*, *sum*, *product* types

# Some Optimizations

- At most one Boolean variable is used for types  $\sigma$  with  $|\sigma| \leq 2$
- On-the-fly simplification of the Boolean formula (e.g. closed HOL formulae simply become `True/False`)
- Hard-coded translation for logical constants
- Specialization of the rule for function application

# Soundness and Completeness

If the SAT solver is sound/complete, we have ...

- *Soundness*: The algorithm returns “model found” only if the given formula has a finite model.
- *Completeness*: If the given formula has a finite model, the algorithm will find it (given enough time).
- *Minimality*: The model found is a smallest model for the given formula.





# Implementation

- Seamless integration with Isabelle/HOL
- Roughly 2,800 lines of ML code
- Several user-definable parameters (e.g. a runtime limit)



# Future Work

- Serious applications:
  - Benchmarks
  - Cryptographic protocols
- Support for other HOL constructs:
  - Inductive datatypes
  - Recursive functions
  - ...
- A better translation:
  - Fewer Boolean variables
  - Shorter Boolean formulae

