

Bounded Model Generation for Isabelle/HOL

*and Related Applications of SAT Solvers in
Interactive Theorem Proving*

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Isabelle

Isabelle is a generic proof assistant:

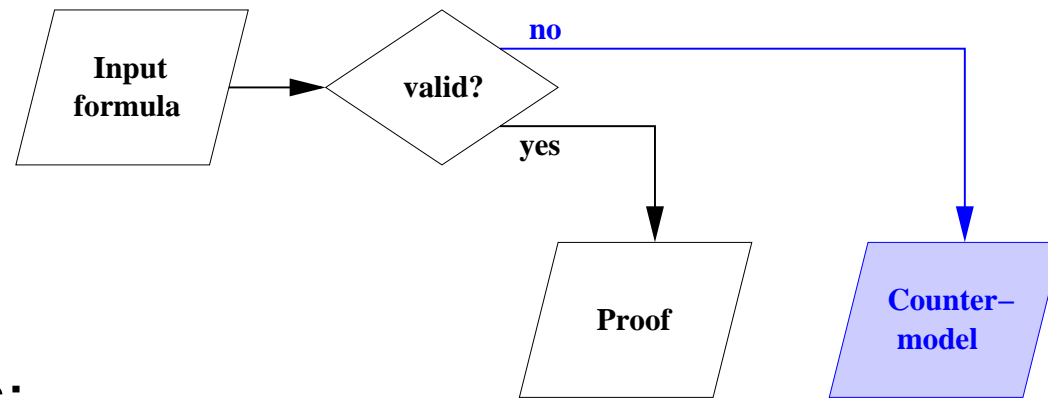
- Highly flexible
- Interactive
- Automatic proof procedures
- Advanced user interface
- Readable proofs
- Large theories of formal mathematics



Bounded Model Generation

Theorem proving: from formulae to proofs

Bounded model generation: *from formulae to models*



Applications:

- *Finding counterexamples to false conjectures*
- Showing the consistency of a specification
- Solving open mathematical problems
- Guiding resolution-based provers

Isabelle/HOL

HOL: higher-order logic based on Church's simple theory of types (1940)

Simply-typed λ -calculus:

- Types: $\sigma ::= \mathbb{B} \mid \alpha \mid \sigma \rightarrow \sigma$
- Terms: $t_\sigma ::= x_\sigma \mid (t_{\sigma' \rightarrow \sigma} t_{\sigma'})_\sigma \mid (\lambda x_{\sigma_1}. t_{\sigma_2})_{\sigma_1 \rightarrow \sigma_2}$

Two logical constants:

- $\implies_{\mathbb{B} \rightarrow \mathbb{B} \rightarrow \mathbb{B}}, \implies_{\sigma \rightarrow \sigma \rightarrow \mathbb{B}}$

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Other constants, e.g.

$\text{True} \mid \text{False} \mid \neg \mid \wedge \mid \vee \mid \forall \mid \exists \mid \exists!$

are definable.



The Semantics of HOL

Set-theoretic semantics:

- Types denote certain sets.
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An *environment* D assigns to each type variable α a non-empty set D_α .

Semantics of types:

- $D(\mathbb{B}) = \{\top, \perp\}$
- $D(\alpha) = D_\alpha$
- $D(\sigma_1 \rightarrow \sigma_2) = D(\sigma_2)^{D(\sigma_1)}$



The Semantics of HOL (2)

A *variable assignment* A maps each variable x_σ to an element $A(x_\sigma)$ in $D(\sigma)$.

Semantics of terms:

- $\llbracket x_\sigma \rrbracket_D^A = A(x_\sigma)$
- $\llbracket (t_{\sigma' \rightarrow \sigma} t_{\sigma'})_\sigma \rrbracket_D^A = \llbracket t_{\sigma' \rightarrow \sigma} \rrbracket_D^A (\llbracket t_{\sigma'} \rrbracket_D^A)$
- $\llbracket (\lambda x_{\sigma_1}. t_{\sigma_2})_{\sigma_1 \rightarrow \sigma_2} \rrbracket_D^A$ is the function that sends each d in $D(\sigma_1)$ to $\llbracket t_{\sigma_2} \rrbracket_D^{A[x_{\sigma_1} \mapsto d]}$
- $\Longrightarrow_{\mathbb{B} \rightarrow \mathbb{B} \rightarrow \mathbb{B}}, =_{\sigma \rightarrow \sigma \rightarrow \mathbb{B}}$: implication, equality

Hence the semantics of a term is an element of the set denoted by the term's type.



Overview

Input: HOL formula ϕ

Output: either a model for ϕ , or “no model found”



Overview

Input: HOL formula ϕ

1. Fix a finite environment D .
2. Translate ϕ into a Boolean formula that is satisfiable iff $\llbracket \phi \rrbracket_D^A = \top$ for some variable assignment A .
3. Use a SAT solver to search for a satisfying assignment.
4. If a satisfying assignment was found, compute from it the variable assignment A . Otherwise repeat for a larger environment.

Output: either a model for ϕ , or “no model found”



Fixing a Finite Environment

Fix a positive integer for every type variable that occurs in the typing of ϕ .

Every type then has a finite size:

- $|\mathbb{B}| = 2$
- $|\alpha|$ is given by the environment
- $|\sigma_1 \rightarrow \sigma_2| = |\sigma_2|^{|\sigma_1|}$

Finite model generation is a generalization of satisfiability checking, where the search tree is not necessarily binary.

The SAT Solver

Several *external* SAT solvers (zChaff, BerkMin, Jerusat, ...) are supported.

- Efficiency
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Simple *internal* solvers are available as well.

- Easy installation
- Compatibility
- Fast enough for small examples

Some Extensions

Sets are interpreted as characteristic functions.

- $\sigma \text{ set} \cong \sigma \rightarrow \mathbb{B}$

- $x \in P \cong P x$

- $\{x. P x\} \cong P$

Non-recursive datatypes can be interpreted in a finite model.

- $(\alpha_1, \dots, \alpha_n)\sigma ::= C_1 \sigma_1^1 \dots \sigma_{m_1}^1 \mid \dots \mid C_k \sigma_1^k \dots \sigma_{m_k}^k$

- $|(\alpha_1, \dots, \alpha_n)\sigma| = \sum_{i=1}^k \prod_{j=1}^{m_i} |\sigma_j^i|$

- Examples: *option*, *sum*, *product* types

Some Extensions

Recursive datatypes are restricted to initial fragments.

- Examples: nat , $\sigma \text{ list}$, lambdaterm
- $\text{nat}^1 = \{0\}$, $\text{nat}^2 = \{0, 1\}$, $\text{nat}^3 = \{0, 1, 2\}$, \dots
- This works for datatypes that occur only positively.

Datatype *constructors* and *recursive functions* can be interpreted as partial functions.

- Examples: $\text{Suc}_{\text{nat} \rightarrow \text{nat}}$, $+\text{nat} \rightarrow \text{nat} \rightarrow \text{nat}$, $@_{\sigma \text{ list} \rightarrow \sigma \text{ list} \rightarrow \sigma \text{ list}}$
- 3-valued logic: true, false, unknown

Axiomatic type classes introduce additional axioms that must be satisfied by the model.

Records and *inductively defined sets* can be treated as well.



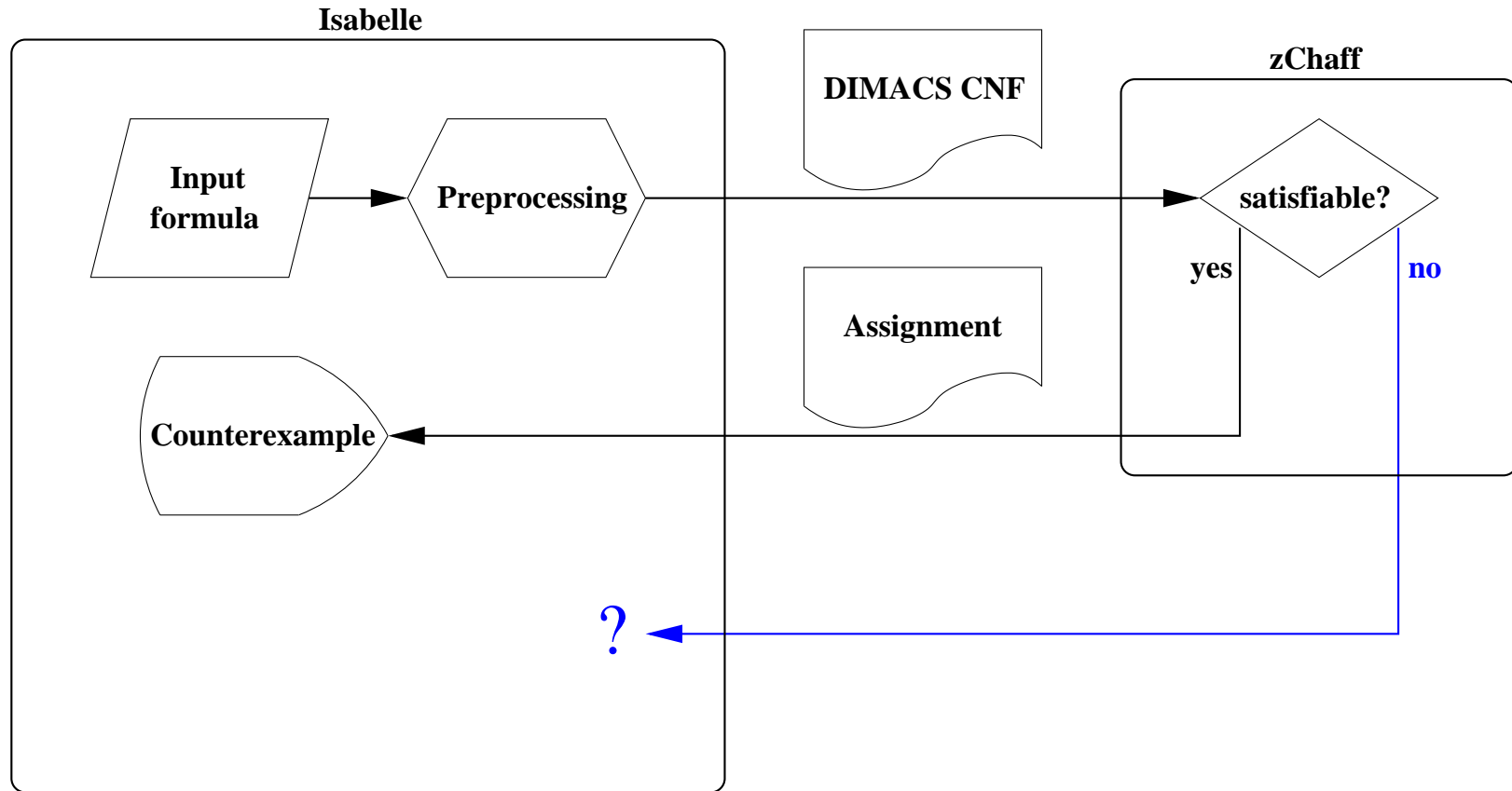
Soundness and Completeness

If the SAT solver is sound/complete, we have ...

- *Soundness*: The algorithm returns “model found” only if the given formula has a finite model.
- *Completeness*: If the given formula has a finite model, the algorithm will find it (given enough time).
- *Minimality*: The model found is a smallest model for the given formula.



“No Model Found”



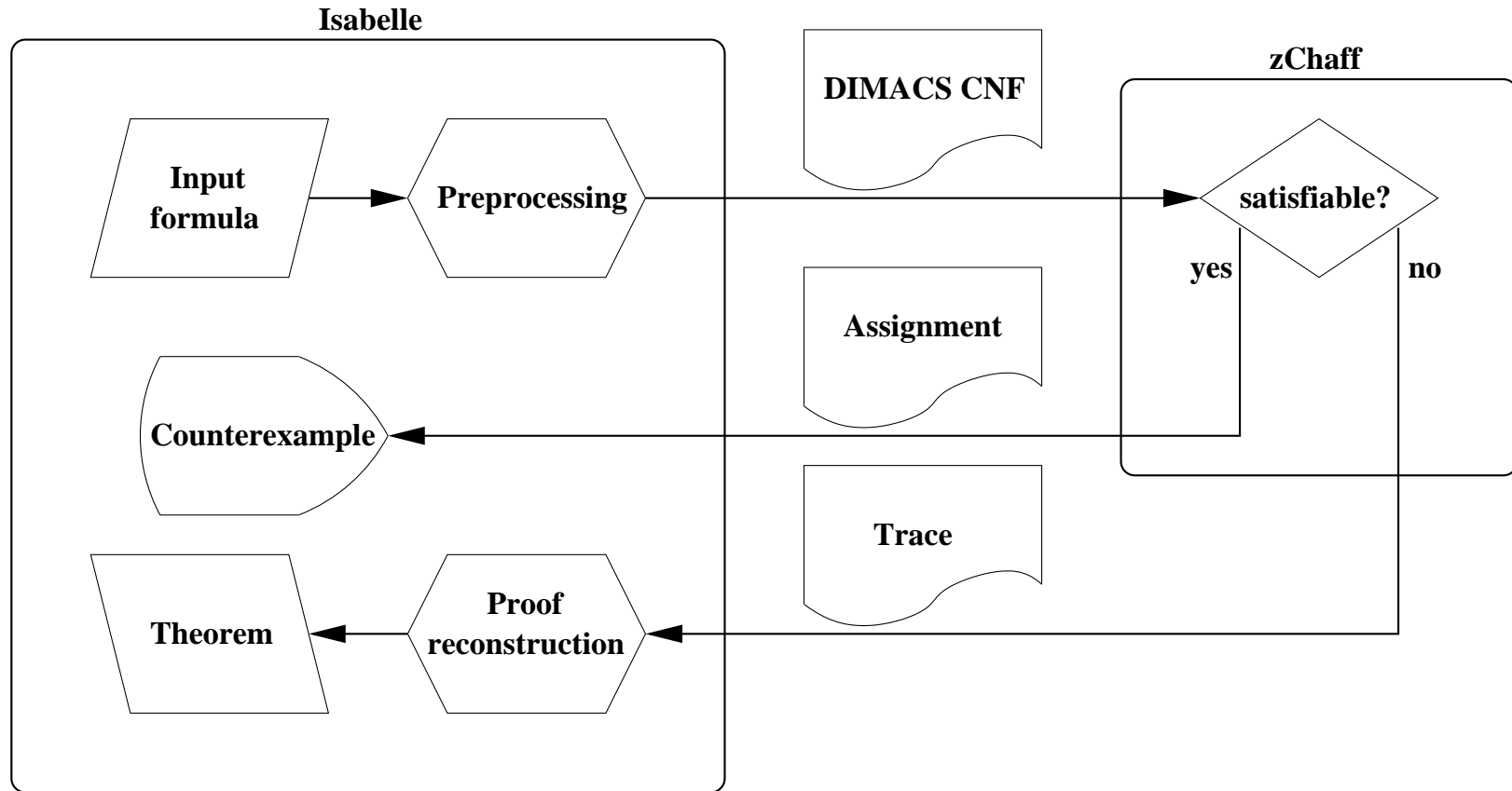
Unsatisfiability – Helpful at All?

- If the Boolean formula is unsatisfiable, the HOL formula ϕ does not have a model of a certain size.
- If ϕ has the finite model property, we can test all models up to the required size.
- If no model is found, $\neg\phi$ must be provable.

Difficult to implement . . . let's only look at *Boolean formulae* for now.



Deciding Boolean Formulae with zChaff



The Algorithm

Preprocessing:

- No conversion from HOL is necessary, only from Boolean logic into CNF.
- But the conversion must be *proof-generating*, i.e. return a theorem $\phi = \phi_{\text{CNF}}$.

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Proof reconstruction:

- zChaff returns a *resolution-style proof* of unsatisfiability.
- The proof is replayed in Isabelle/HOL to derive $\neg\phi$.



Performance

- Isabelle is several orders of magnitude slower than zverify_df.
- However, zChaff vs. auto/blast/fast ...
 - 42 propositional problems in TPTP, v2.6.0
 - 19 “easy” problems, solved in less than a second each by auto, blast, fast, and zchaff_tac
 - 23 harder problems



Performance

Problem	Status	auto	blast	fast	zChaff
MSC007-1.008	unsat.	x	x	x	726.5
NUM285-1	sat.	x	x	x	0.2
PUZ013-1	unsat.	0.5	x	5.0	0.1
PUZ014-1	unsat.	1.4	x	6.1	0.1
PUZ015-2.006	unsat.	x	x	x	10.5
PUZ016-2.004	sat.	x	x	x	0.3
PUZ016-2.005	unsat.	x	x	x	1.6
PUZ030-2	unsat.	x	x	x	0.7
PUZ033-1	unsat.	0.2	6.4	0.1	0.1
SYN001-1.005	unsat.	x	x	x	0.4
SYN003-1.006	unsat.	0.9	x	1.6	0.1
SYN004-1.007	unsat.	0.3	822.2	2.8	0.1
SYN010-1.005.005	unsat.	x	x	x	0.4
SYN086-1.003	sat.	x	x	x	0.1
SYN087-1.003	sat.	x	x	x	0.1
SYN090-1.008	unsat.	13.8	x	x	0.5
SYN091-1.003	sat.	x	x	x	0.1
SYN092-1.003	sat.	x	x	x	0.1
SYN093-1.002	unsat.	1290.8	16.2	1126.6	0.1
SYN094-1.005	unsat.	x	x	x	0.8
SYN097-1.002	unsat.	x	19.2	x	0.2
SYN098-1.002	unsat.	x	x	x	0.4
SYN302-1.003	sat.	x	x	x	0.4

Conclusions and Future Work

- Finite countermodels for HOL formulae
- A fast decision procedure for Boolean formulae
- Further optimizations, benchmarks
- A SAT-based decision procedure for a fragment of HOL
- Integration of external model generators
- ...

