

Frequentist Techniques for Parameter Estimation

Observed model response

$$y = f(X, q)$$

Observations

$$y_i = f(X_i, q) + \varepsilon_i, \quad i=1, \dots, n$$

↙ measurement errors

Determine q in a stable manner from y
inverse uncertainty quantification

Evolution process

$$\begin{aligned} \frac{\partial u}{\partial t} &= \mathcal{N}(u, q) + F(q), & x \in D, t \geq t_0 \\ \mathcal{B}(u, q) &= G(q), & x \in \partial D, t \geq t_0 \\ u(t_0, x, q) &= I(q), & x \in D \end{aligned}$$

$$\Rightarrow f(q) = (f(t_1, q), \dots, f(t_n, q))^T$$

$$Y = f(q_0) + \delta + \varepsilon, \quad \text{random vector with realization } y$$

↙ model errors

Frequentist assumption: parameters are fixed q_0
but possibly unknown

q_0 given parameter value, generating y

Calibration of model with q such that $f(q)$ is close to data

estimator \hat{q}

$$\hat{q}_{OLS} = \arg \min_{q \in \mathcal{Q}} \sum_{i=1}^n (Y_i - f_i(q))^2 \quad \begin{array}{l} \text{Ordinary} \\ \text{Least} \\ \text{Squares} \end{array}$$

↑ random vector

Require $E(\hat{q}) = q_0$, variance quantifies variability of errors

does not provide distribution for model parameters, q_0 is not a random variable

Linear regression

$$Y = Xq_0 + \varepsilon, \quad X \in \mathbb{R}^{n \times p} \quad \begin{array}{l} \text{measurements} \\ \downarrow \\ n > p \end{array} \quad \begin{array}{l} \text{parameters} \\ \swarrow \end{array}$$

$\text{rank } X = p \Rightarrow q_0$ is identifiable, $R(X^T) = \mathbb{R}^p$

Errors ε are unbiased and iid with variance σ_0^2

$$\Rightarrow 1. E(\varepsilon_i) = 0$$

$$2. \text{Var}(\varepsilon_i) = \sigma_0^2, \text{Cov}(\varepsilon_i, \varepsilon_j) = 0, i \neq j$$

fixed, unknown

Goal: unbiased estimators $\hat{q}, \hat{\sigma}^2$ for q_0, σ_0^2

$$J(q) = (Y - Xq)^T (Y - Xq)$$

$$\min J(q) \Rightarrow \nabla_q J = 2 \left(\nabla_q (Y - Xq)^T \right) (Y - Xq) = 0$$

$$-\nabla_q q^T X^T = -X^T$$

$$\Rightarrow X^T Y = X^T X q \Rightarrow \hat{q} = \underbrace{(X^T X)^{-1}}_A X^T Y = AY$$

with realization

$$q = (X^T X)^{-1} X^T y$$

mean value

$$1. E(\hat{q}) = E((X^T X)^{-1} X^T Y) = (X^T X)^{-1} X^T E(Y) =$$

$$\{ E(Y) = E(Xq_0) + E(\varepsilon) = Xq_0 \} = q_0$$

covariance matrix

$$2. V(\hat{q}) = E((\hat{q} - q_0)(\hat{q} - q_0)^T) =$$

$$\{ \hat{q} = AY = AXq_0 + A\varepsilon = q_0 + A\varepsilon \}$$

$$= A \underbrace{E(\varepsilon \varepsilon^T)}_{\sigma_0^2 I} A^T = \sigma_0^2 (X^T X)^{-1} X^T X (X^T X)^{-1} = \sigma_0^2 (X^T X)^{-1}$$

Unbiased covariance estimator

$$\hat{\sigma}^2 = \frac{1}{n-p} \hat{R}^T \hat{R}, \quad \hat{R} = Y - X\hat{q} = Y - X(X^T X)^{-1} X^T Y$$

cf. standard deviation (sample variance) $p=1$

Sampling distribution for \hat{q}

Assume errors normally distributed or large number of samples to apply central limit theorem

Errors are iid and $\varepsilon_i \sim N(0, \sigma_0^2)$

$$\Rightarrow \hat{q} \sim N(q_0, \sigma_0^2 (X^T X)^{-1})$$

Normal distribution specified by $E(\hat{q})$, $V(\hat{q})$

Errors may be iid with variance σ_0^2 but not normally distributed.

For large sample sizes use central limit theorem
 \Rightarrow as above

Confidence intervals for mean of \hat{q}

$$p=1, X = (1, 1, \dots, 1)^T, Y_i \sim N(\mu_0, \sigma_0^2)$$

$$\hat{q} = \frac{1}{n} \sum_{i=1}^n Y_i, E[\hat{q}] = \mu_0, V(\hat{q}) = \frac{\sigma_0^2}{n}, \hat{q} \sim N(\mu_0, \frac{\sigma_0^2}{n})$$

$$q = \frac{\sqrt{n}(\hat{q} - \mu_0)}{\sigma_0} \sim N(0, 1), S^2 = \frac{1}{n-1} \sum_{i=1}^n (Y_i - \hat{q})^2$$

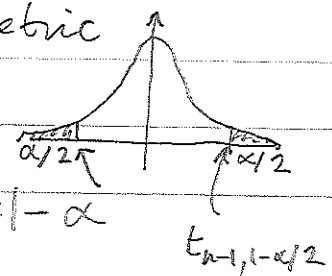
$$S^2 \sim \frac{\sigma_0^2}{n-1} \chi^2(n-1) \Rightarrow Z = \frac{(n-1)S^2}{\sigma_0^2} \sim \chi^2(n-1)$$

$$\Rightarrow T = \frac{q}{\sqrt{Z/(n-1)}} = \frac{\sqrt{n}(\hat{q} - \mu_0)}{S} \quad \begin{array}{l} \text{Student's } t \\ \text{is } t\text{-distributed, } n-1 \\ \text{symmetric} \end{array}$$

$$P(a < \frac{\sqrt{n}(\hat{q} - \mu_0)}{S} < b) = 1 - \alpha$$

$$P\left(\hat{q} - \frac{t_{n-1, 1-\alpha/2}}{\sqrt{n}} S < \mu_0 < \hat{q} + \frac{t_{n-1, 1-\alpha/2}}{\sqrt{n}} S\right) = 1 - \alpha$$

probability that μ_0 is in the interval



Nonlinear models

$$Y = f(q_0) + \epsilon$$

ϵ_i iid, $E(\epsilon_i) = 0$, $Var(\epsilon_i) = \sigma_0^2$

estimator

$$\hat{q} = \underset{q \in Q}{\operatorname{argmin}} \sum_{i=1}^n (Y_i - f_i(q))^2$$

estimate

$$q = \underset{q \in Q}{\operatorname{argmin}} \sum_{i=1}^n (y_i - f_i(q))^2$$

nonlinear least squares problem $\Rightarrow X^T(q_0)(y - f(q_0)) = 0$

Linearization around q_0 , $X_{ij}(q) = \frac{\partial f_i}{\partial q_j}(q)$

$$V(\hat{q}) \approx \sigma_0^2 (X^T(q_0)X(q_0))^{-1}, \hat{q} = q_0 + \delta q$$

1. $X_{ij}(q) \approx \frac{f_i(q+h_j) - f_i(q)}{|h_j| \leftarrow h}$, $h_j = h \begin{pmatrix} 0 \\ \vdots \\ 1 \\ \vdots \\ 0 \end{pmatrix} \leftarrow j$

2. Automatic differentiation (AD)

Sampling distribution

$$\hat{q} \sim N(q_0, \sigma_0^2 (X^T(q_0)X(q_0))^{-1}), q_0 = E(\hat{q})$$

Confidence intervals in the same manner

Exercise: 7.6

$$Y = f(q_0 + \delta q) + \epsilon = f(q_0) + X \delta q + \epsilon + O(\|\delta q\|^2)$$
$$Y - f(q_0) = X \delta q + \epsilon$$

$$J(q_0 + \delta q) = (Y - f(q_0) - X_0 \delta q)^T (Y - f(q_0) - X_0 \delta q)$$

$$\nabla_{\delta q} J = -2 X_0^T (Y - f(q_0) - X_0 \delta q) = 0$$

$$\Rightarrow X_0^T X_0 \delta q = X_0^T (Y - f(q_0))$$

$$\delta q = \underbrace{(X_0^T X_0)^{-1}}_A \underbrace{X_0^T (Y - f(q_0))}_\varepsilon$$

$$E(\delta q) = E(A \varepsilon) = A E(\varepsilon) = 0$$

$$V(\delta q) = \sigma_0^2 (X^T X)^{-1}$$

$$\hat{q} = q_0 + \delta q \Rightarrow E(\hat{q}) = q_0, \quad \hat{q} = q_0 + A \varepsilon$$

$$V(\hat{q}) = E((\hat{q} - q_0)(\hat{q} - q_0)^T) = A E(\varepsilon \varepsilon^T) A^T = \sigma_0^2 (X^T X)^{-1}$$

UQ5

Bayesian techniques for parameter estimation

$$Y_i = f_i(Q) + \varepsilon_i, \quad i=1 \dots n, \quad \varepsilon_i \text{ unbiased iid}$$

Y_i, ε_i, Q random variables

Parameters random variables, realizations $q = Q(\omega)$
 Q has density, updated by incoming data
 \Rightarrow posterior density for Q (based on sampled observations)

prior density, likelihood \Rightarrow posterior density

$$\pi_0(q) \quad \pi(y|q) \quad \pi(q|y)$$

$\pi_0(q)$ knowledge obtained before observations y
 noninformative prior $\pi_0(q) = \chi_{(0, \infty)}(q)$

$$\chi_{(a,b)}(q) = \begin{cases} 1, & q \in (a,b) \\ 0, & \text{otherwise} \end{cases} \quad \text{indicator function}$$

$\pi(y|q) = L(q|y)$ (based on information from samples)

$\pi(q, y)$ joint density of Q and Y

$$\pi(y|q) = \frac{\pi(q, y)}{\pi_0(q)}$$

$\Rightarrow \pi(q|y_{\text{obs}}) = \frac{\pi(q, y_{\text{obs}})}{\pi(y_{\text{obs}})}$ posterior density

$$\pi(y_{\text{obs}}) = \int_{\mathbb{R}^p} \pi(q, y_{\text{obs}}) dq = \int_{\mathbb{R}^p} \pi(y_{\text{obs}}|q) \pi_0(q) dq$$

Q has prior density $\pi_0(q)$

$$\pi(q|y_{obs}) = \frac{\pi(y_{obs}|q)\pi_0(q)}{\pi(y_{obs})} = \frac{\pi(y_{obs}|q)\pi_0(q)}{\int_{\mathbb{R}^p} \pi(y_{obs}|q)\pi_0(q) dq}$$

$$\Rightarrow \int_{\mathbb{R}^p} \pi(q|y_{obs}) dq = 1 \quad \text{wie bei 4}$$

Likelihood function ($y = y_{obs}$ from now on)
 $\epsilon_i \sim N(0, \sigma^2)$, iid, σ^2 fixed

$$\pi(y|q) = L(q, \sigma^2|y) = \frac{1}{(2\pi\sigma^2)^{n/2}} e^{-SS_q/2\sigma^2}$$

$$SS_q = \sum_{i=1}^n (y_i - f_i(q))^2 \quad \prod_{i=1}^n e^{-\frac{(y_i - f_i(q))^2}{2\sigma^2}}$$

Maximum a posteriori (MAP) estimate

$$q_{MAP} = \underset{q}{\operatorname{argmax}} \pi(q|y)$$

normalization $\pi(y)$ does not change the max

$$\Rightarrow q_{MAP} = \underset{q}{\operatorname{argmax}} \pi(y|q)\pi_0(q)$$

$\pi_0(q)$ uniform on $\mathbb{R} \Rightarrow$

$$q_{MAP} = q_{MLE} = \underset{q}{\operatorname{argmax}} \pi(y|q)$$

Take $\pi_0(q) = \chi_{[0, \infty)}(q)$

$$\Rightarrow \pi(q|y) = \frac{e^{-SS_q/2\sigma^2}}{\int_0^\infty e^{-SS_s/2\sigma^2} ds} = \frac{1}{\int_0^\infty e^{-(SS_s - SS_q)/2\sigma^2} ds}$$