

Representation of random inputs (§5)
parameter $\alpha(x, \omega)$ in

$$\frac{\partial T}{\partial t} = \frac{\partial}{\partial x} \left(\alpha(x, \omega) \frac{\partial T}{\partial x} \right) + f(t, x)$$

$\alpha(x, \omega)$ infinite-dimensional
approximate by finite-dimensional expansion

$Q = (Q_1, \dots, Q_p)$, p mutually independent
 $Q_i(\omega) = \Omega \rightarrow \mathbb{R}$ with density $f_{Q_i}(q_i)$
independent $\Rightarrow f_Q(q) = \prod_{i=1}^p f_{Q_i}(q_i)$

Approximate $\alpha(x, \omega)$ by
$$\alpha(x, \omega) \approx \bar{\alpha}(x) + \sum_{n=1}^N Q_n(\omega) \phi_n(x)$$

We want:

Q_n mutually independent
small N , densities $f_{Q_n}(q_n)$
 $\bar{\alpha}(x) = \mathbb{E}[\alpha(x, \omega)]$, $\phi_n(x)$ basis functions
 $Q = (Q_1, \dots, Q_n)$ mutually indep. random var.

Karhunen-Loève expansions (PCA, principal component analysis, POD, proper orthogonal decomposition)
$$\alpha(x, \omega) = \bar{\alpha}(x) + \sum_{n=1}^{\infty} \sqrt{\lambda_n} \phi_n(x) Q_n(\omega)$$

$\mathbb{E}(\alpha(x, \omega)) = \bar{\alpha}(x)$, $\text{Cov}(\alpha(x, \omega), \alpha(y, \omega)) = C(x, y)$
correlation in space

λ_n, ϕ_n eigenvalues and orthonormal eigenfunctions
of C

$$\int_D C(x, y) \phi_n(y) dy = \lambda_n \phi_n(x)$$

$$Q_n(\omega) = \frac{1}{\sqrt{\lambda_n}} \int_D (\alpha(x, \omega) - \bar{\alpha}(x)) \phi_n(x) dx$$

$$E(Q_n) = 0, \quad E(Q_m Q_n) = \delta_{mn}$$

Truncated K-L expansion for numerical purposes
$$\alpha(x, \omega) = \bar{\alpha}(x) + \sum_{n=1}^N \sqrt{\lambda_n} \phi_n(x) Q_n(\omega)$$

Parameter selection techniques §6

Identifiable parameters

$$y = f(q), \quad q = (q_1, q_2, \dots, q_p)$$

q is identifiable at q^* if $f(q) = f(q^*) \Rightarrow q = q^*$
for any admissible $q \in Q$

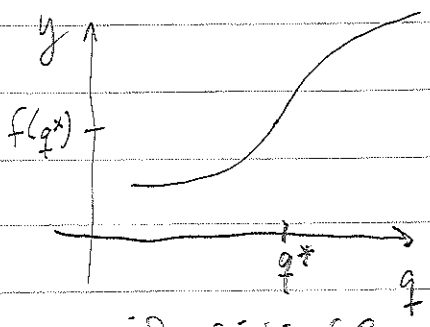
q is identifiable with respect to space $I(q)$
if this holds for all $q^* \in I(q)$ (identifiable subspace)

unidentifiable subspace $NI(q)$ is orthogonal complement to $I(q)$ ($x \in NI(q) \Rightarrow x \perp I(q)$)

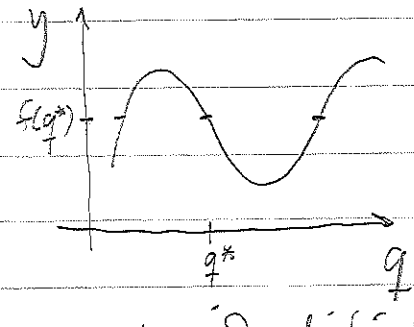
$$\Rightarrow Q = I(q) \oplus NI(q)$$

Influential parameters

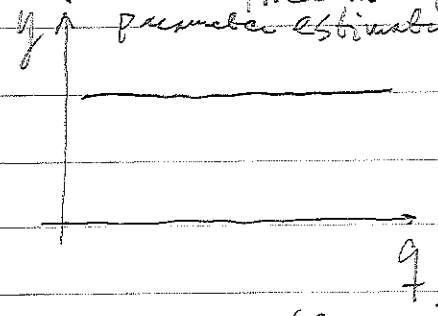
q is uninfluential if $\forall q$ and $q^* \in NI(q)$
 $|y(q) - y(q^*)| < \epsilon$ for all q and $q^* \in NI(q)$
can be fixed in parameter estimation



q identifiable



q unidentifiable



q uninfluential

Linearly parameterized problems

$$y = Aq, \quad q \in \mathbb{R}^p, \quad y \in \mathbb{R}^n, \quad A \in \mathbb{R}^{n \times p}$$

usually $p \geq n$ $y| = \boxed{A} | q$

identifiable subspace $I(q) = \mathcal{R}(A^T) = \mathcal{R}(A^T A)$

unidentifiable subspace $NI(q) = \mathcal{N}(A) = \mathcal{N}(A^T A)$

Singular Value Decomposition (SVD)

$$A = U \Sigma V^T, \quad U \in \mathbb{R}^{n \times n}, \quad V \in \mathbb{R}^{p \times p}$$

$$\Sigma = \begin{bmatrix} S & 0 \end{bmatrix} \in \mathbb{R}^{n \times p}$$

orthogonal columns

$$S = \begin{pmatrix} \sigma_1 & & & 0 \\ & \sigma_2 & & \\ & & \ddots & \\ 0 & & & \sigma_r \\ & & & & 0 \end{pmatrix}, \quad \sigma_1 \geq \sigma_2 \geq \dots \geq \sigma_r \geq \epsilon$$

numerical rank r

$$U = [U_r \ U_{n-r}], \quad U_r \in \mathbb{R}^{n \times r}, \quad U_{n-r} \in \mathbb{R}^{n \times (n-r)}$$

$$V = [V_r \ V_{p-r}], \quad V_r \in \mathbb{R}^{p \times r}, \quad V_{p-r} \in \mathbb{R}^{p \times (p-r)}$$

$$\Rightarrow A = \begin{bmatrix} U_r & U_{n-r} \end{bmatrix} \begin{bmatrix} S_r & 0 \\ 0 & 0 \end{bmatrix} \begin{bmatrix} V_r^T \\ V_{p-r}^T \end{bmatrix} = U_r S_r V_r^T$$

$$S_r = \begin{pmatrix} \sigma_1 & & & 0 \\ & \sigma_2 & & \\ & & \ddots & \\ 0 & & & \sigma_r \\ & & & & 0 \end{pmatrix}$$

$$V = V_{p-r} V \Rightarrow AV = AV_{p-r} V = 0 \Rightarrow \mathcal{N}(A) = V_{p-r}$$

$v = S_r^{-1} U_r^T \mu \Rightarrow S_r^T v = U_r^T \mu = U_r^T U_r \xi \Rightarrow \mu = U_r S_r^T v$

$$A^T = V_r S_r U_r^T \Rightarrow v = V_r v = V_r S_r U_r^T \mu = A^T \mu$$

$$\Rightarrow \mathcal{R}(A^T) = V_r \Rightarrow I(q) = V_r, \quad NI(q) = V_{p-r}$$

QR algorithms

$$A^T = QR = \begin{matrix} n \\ \boxed{} \end{matrix} \begin{matrix} n \\ \boxed{P} \end{matrix} = \begin{matrix} n \\ \boxed{} \end{matrix} \begin{matrix} n \\ \boxed{P} \end{matrix} \begin{matrix} n \\ \boxed{} \end{matrix}$$

$R(A^T) = Q$ if A has full rank
 $N(A) = \tilde{Q} \in \mathbb{R}^{(p-n) \times p}$, $\tilde{Q}^T Q = 0$

Random algorithms

SVD, QR are applicable for small A

Stage 1: Construct low dimensional subspace where products $y = Aq$ can be computed, approximate range of A by orthonormal matrix Q of rank r such that

$$\|A - QQ^T A\|_2 \leq \epsilon \quad \left(\begin{array}{l} \text{if } A = QR, R(A) = Q \\ A - QQ^T QR = A - QR = 0 \end{array} \right)$$

r as small as possible (random part)

Stage 2: Use SVD or QR and Q to approximate A (deterministic part)

$$B = Q^T A = \tilde{U} \Sigma V^T$$

$$U = Q \tilde{U} \Rightarrow QB = \underbrace{QQ^T}_I A = Q \tilde{U} \Sigma V^T = U \Sigma V^T$$

$U^T U = \tilde{U}^T Q^T Q \tilde{U} = I$ $\approx A$ in stage 1

Random Range Finder

1. l random q^i , compute $y^i = Aq^i \rightarrow Y = (y^1, y^2, \dots, y^l)$
2. $Y = QR$, Q^T has columns forming an orthonormal basis for $R(Y) \Rightarrow Q$ in stage 1

Nonlinearly parameterized problems

$$y = f(q)$$

local sensitivity matrix

$$X_{ij} = \frac{\partial f_i}{\partial q_j}(q^*)$$

linearize around q^*

local parameter identifiability in neighborhood of q^*

Exercise 6.3