

Defuzzification Based on Feature Distance Minimization

Fuzzy Sets and Fuzzy Techniques
Lecture 13

Nataša Sladoje

Outline

Introduction

- Fuzzy sets in image processing
- Defuzzification

Defuzzification by feature distance minimization

- Feature distance minimization
- Defuzzification at increased spatial resolution
- Scale space approach
- Extension to 3D

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Fuzzy sets in image processing

- In the digitization process, fuzzy representations preserve information about the original object better than crisp representations.
- At the same spatial resolution, many object **features** can be estimated with a higher precision from a fuzzy representation than from a crisp representation.

Among them are:

- area / volume
- perimeter / surface area
- geometric moments



crisp



fuzzy

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Sometimes crisp is required

Reasons to use a crisp representation may be:

- to provide easier and less subjective interpretation of images, especially if the dimension of the image is higher than 2;
- in cases when fuzzy image analysis tools are not yet developed, while crisp analogues exist.

Defuzzification

to generate a crisp representation of a fuzzy set.



crisp



fuzzy

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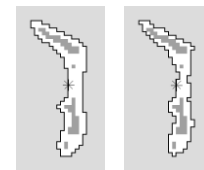
Defuzzification by α -cutting

Thresholding of the membership function.

An example:



A part of a microscopy image of a bone implant. Original and a fuzzy segmented bone region.



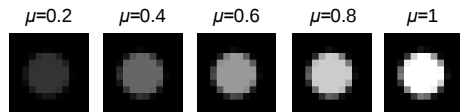
α -cut at $\alpha=0.25$ α -cut at $\alpha=0.5$ α -cut at $\alpha=0.75$

Which α to choose?

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Defuzzification by minimizing point-wise difference



↓ defuzzification



Stability?

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Defuzzification by feature distance minimization

Defuzzification formulated as an optimization problem

Definition: An optimal defuzzification of a fuzzy set A is a crisp set C (on the reference set X) such that the distance between A and C is minimal:

$$\mathcal{D}(A) \in \{C \in \mathcal{P}(X) \mid d(A, C) = \min_{B \in \mathcal{P}(X)} [d(A, B)]\}.$$

Find the crisp set closest to the given fuzzy set.

- Which distance to use?
- How to perform the optimization?

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Feature distance

- Extract **both** local and global "features" of the sets.
- Make a vector representation of each set using the extracted features.
- Measure the distance between two sets in this high dimensional feature space.

The **feature distance** between sets A and B , with feature representations $\Phi(A)$ and $\Phi(B)$, is

$$d^\Phi(A, B) = d(\Phi(A), \Phi(B)).$$

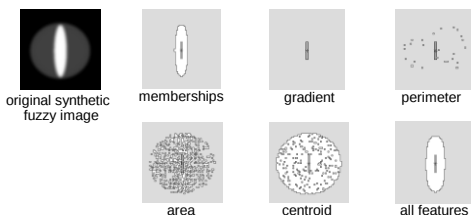
We use the Minkowski distance, with $p=1$, as distance measure in the feature space.

$$d_p(\mathbf{x}, \mathbf{y}) = \left(\sum_{i=1}^n |x_i - y_i|^p \right)^{1/p}$$

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Examples of defuzzification based on different features



A combination of many features provides a good defuzzification result.

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Minimizing the distance

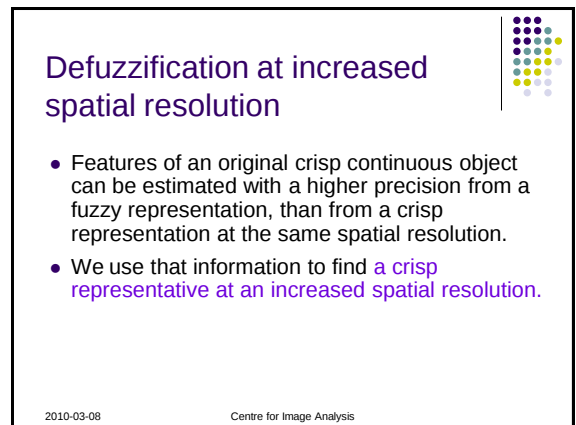
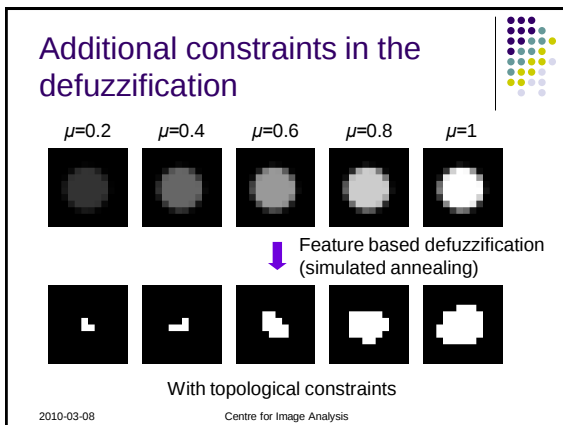
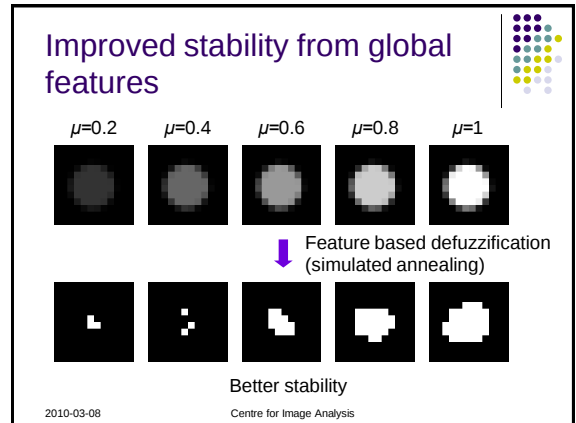
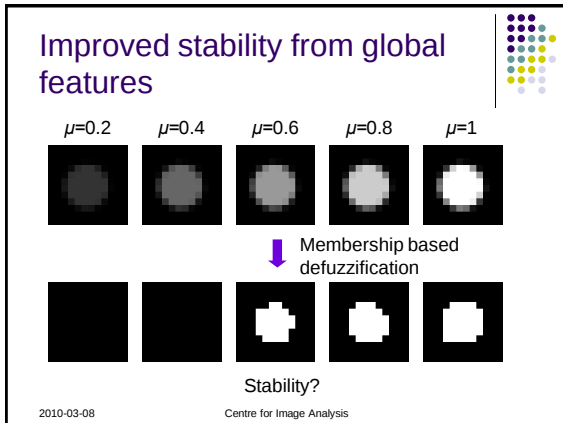
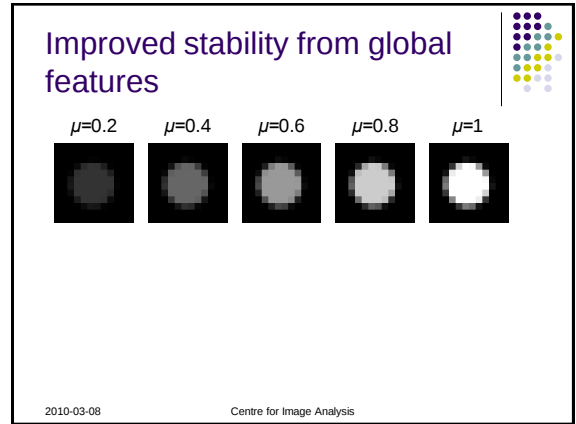
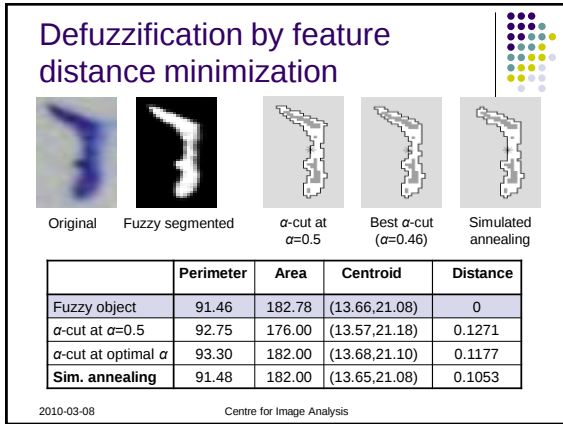
- An analytic solution is, in general, not known.
- 2^n configurations – exhaustive search is not an option.
- Some heuristics must be applied.

Simulated annealing has shown to provide a good trade off between speed and performance.

The **optimal α -cut** provides a fast alternative (and a good starting point for the simulated annealing).

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Distance between sets at different resolution

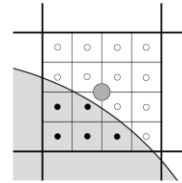
De-couple the feature representation from the image resolution.

- Global features
 - By proper rescaling of the feature values.
- Local features
 - By comparing individual pixels of the lower resolution image, with blocks of pixels of the higher resolution image.

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Membership value – area of a block of pixels



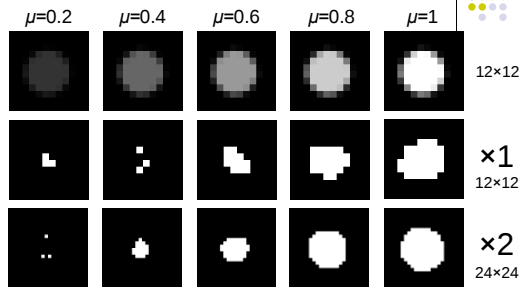
The membership value of a fuzzy pixel corresponds to the area of a block of $r \times r$ crisp sub-pixels.

Fuzzy membership is (approximately) 5/16.
Area of the block of (crisp) subpixels is $5 \times 1/16$

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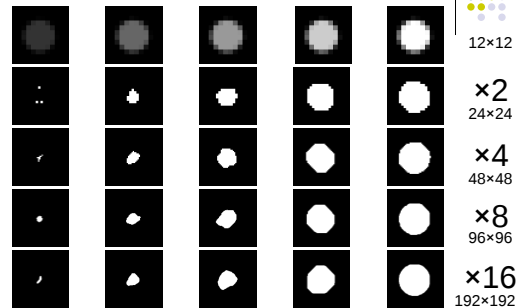
High resolution defuzzification



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High resolution defuzzification



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High resolution defuzzification



Fuzzy disk
12 x 12 pixels
8bits per pixel
=1152 bits

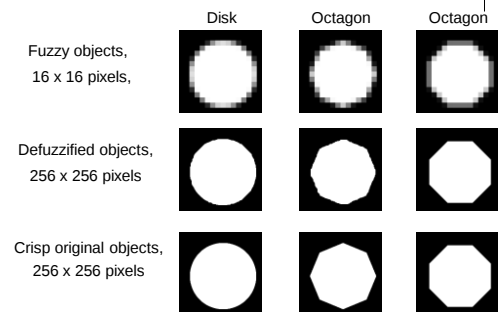
Defuzzified set
192 x 192 pixels
32 times more information!

Crisp disk
192 x 192 pixels
1bit per pixel
=36 864bits

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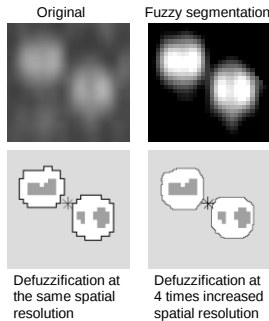
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High resolution reconstruction disk vs. octagon



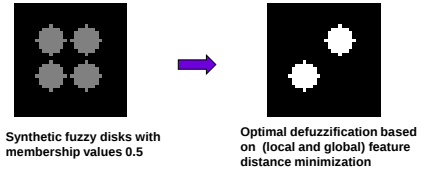
Realistic example: Blood vessels

A fuzzy segmentation, and defuzzifications, of a slice in a 3D MRA of a human aorta, where it separates into the two iliac arteries.



Motivation for a scale space approach

- Example with four discrete fuzzy disks



Perimeter, area and centroid are all perfectly matched!

The method can "transport" area from one part of the image to another.

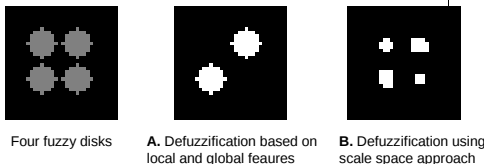
Meso-scale features

- Meso-scale is scale in-between the local (pixel-size) and the global (the whole object) scale.
- Characteristics of a fuzzy set often have different importance at different scales.
- Our first choice of feature to observe at meso-scale is area (volume in 3D case).

Feature vector representation for scale space defuzzification

- Features included in the vector representation of a 2D fuzzy set are
 - Area, at a number of scales (including pixel-size, and global)
 - Perimeter
 - Centroid
- Resolution pyramid representation of sets is utilized for storing areas of blocks of pixels.
- Comparison of meso-scale areas reduces to a comparison of the corresponding pixels in the sets at corresponding levels of the resolution pyramid.
- All measures are appropriately rescaled.

Defuzzification of 4 circles



	Perimeter	Area	Centroid	Membership	Meso-scale	Dist 1	Dist 2
A.	0.0000	0.0000	0.0000	0.0957	0.3828	0.0957	0.4785
B.	0.0015	0.0381	0.0000	0.0957	0.1758	0.1353	0.3111

Contribution of different features to the distance measure.
Dist1 without meso-scale, Dist2 with meso-scale features.

Scale space defuzzification of 3D fuzzy sets

- Defuzzification method for 2D fuzzy sets is straightforwardly generalized to the 3D case.
- The features included in the 3D defuzzification are local, meso-scale, and global volumes, obtained by iterative grouping of blocks of $2 \times 2 \times 2$ voxels, together with surface area and centroid.
- Larger search space puts additional demands on the efficiency of the optimization method.
 - Simulated annealing with re-annealing is a reasonable option, if started from an optimal α -cut.

3D Example - image of a bone implant

Slice through the 3D image



Slice through the 3D fuzzy segmentation



Slice through the 3D defuzzification



Rendering of the optimal α -cut defuzzification



Rendering of defuzzification (simulated annealing) at four times the original resolution

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3D rendering of the optimal defuzzification



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Instead of a conclusion...

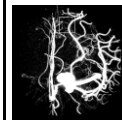
A better solution to a crisp problem is found by looking first in a larger space of **fuzzy sets**

which has different (usually less) constraints and therefore allows the algorithms **more freedom** and **reduces errors** caused by forced crisp answers at intermediate steps.

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3D Example – X-ray scan of the arteries of the right half of a human head



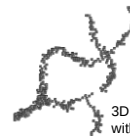
MIP through the image volume



MIP through a selected part of the image



3D rendering of defuzzification using under-estimated surface area.



3D rendering of defuzzification without meso-scale volume



3D rendering of defuzzification with meso-scale volume

3D rendering of a defuzzification using only volume at all scales



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