Chapter 34: P versus NP, A Gentle Introduction (Version of 14th December 2023)

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Course 1DL231: Algorithms and Data Structures 2 (AD2)





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NP Completeness Relationships

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(Cook, 1971; Levin, 1973)

This is one of the seven Millennium Prize problems of the Clay Mathematics Institute (Massachusetts, USA), each worth 1 million US\$.

Informally:

- P = class of problems that need no search in order to be solved NP = class of problems that might need search in order to be solved
- P = class of problems with easy-to-compute solutions

NP = class of problems with easy-to-check solutions

Thus: Can search always be avoided (P = NP), or is search sometimes necessary ($P \neq NP$)?

Computational tasks that are doable in polynomial time (in the input size) are said to be tractable or easy.

Tasks requiring non-polynomial time are said to be intractable or hard.



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P and NP: Definitions and Examples

A bit more formally, and focussing on decision problems for NP, whose answer is 'yes' or 'no', for inputs of size *n*:

- P = the class of easy problems, whose solutions can be computed in polynomial time: O(n^k) time for some fixed k.
 Examples: sorting; almost all problems in this course.
- NP = the class of problems where a witness can be checked in polynomial time when the answer is 'yes'. NP stands not for "*non-p*olynomial time", but for "*non-deterministic polynomial time*". We trivially have P ⊆ NP.
 Example: Given an *n*-digit number, does it have a divisor ending in 7? Computing such a divisor seems hard, but checking a witness, that is a candidate divisor, is easy.
- Undecidable problems cannot be solved by any algorithm, no matter how much time is allocated. Examples: halting problem; disjointness of CFLs.
 So not all problems are in NP, independently of P versus NP.

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Reduction and NP Hardness

Informally:

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A problem Q reduces to a problem R, denoted Q ≤_P R, if every instance of Q can be transformed in *p*olynomial time into an instance of R that has the same yes/no answer. We also say that R is at least as hard as Q. Note that ≤_P is transitive: ∀Q, E, R : Q ≤_P E ≤_P R ⇒ Q ≤_P R.

(Karp, 1972)

- Proving that a problem Q is in P can be done by showing that Q ≤_P E for some existing problem E in P.
- A problem is NP-hard if it is at least as hard as every problem in NP: we have that every problem in NP reduces to an NP-hard problem.
- On slide 19 is a wider definition of NP hardness.



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(Cook, 1971; Levin, 1973)

Formally:

A problem is NP-complete if it is in NP and is NP-hard.

If some NP-complete problem is polynomial-time solvable, then every problem in NP is polynomial-time solvable: $P \supseteq NP$ and so P = NP.

An NP-complete problem is polynomial-time solvable if and only if P = NP.

If some problem in NP is not polynomial-time solvable (P \neq NP), then no NP-complete problem is polynomial-time solvable.

The status of NP-complete problems is currently unknown: No polynomial-time algorithm was found for any of them, and no proof was made that no such algorithm can exist.

Most experts believe NP-complete problems are intractable, as the opposite would be truly amazing.



NP Completeness: Examples

Given a digraph (V, E) and two vertices $u, v \in V$:

Examples

- Finding a shortest path from u to v takes $\mathcal{O}(V \cdot E)$ time and is thus in P.
- Determining the existence of a simple path (which has distinct vertices) that has at least a given number l of edges is NP-complete. Hence finding a longest path seems hard:

increase ℓ starting from a trivial lower bound, until the answer is 'no'.

Examples

- Finding an Euler tour (which visits each *edge* once) takes O(E) time and is thus in P.
- Determining the existence of a Hamiltonian cycle (which visits each vertex once) is NP-complete.

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NP Completeness: More Examples

Examples

- 2-SAT: Determining the satisfiability of a conjunction of disjunctions of 2 Boolean literals is in P.
- 3-SAT: Determining the satisfiability of a conjunction of disjunctions of 3 Boolean literals is NP-complete.
- SAT: Determining the satisfiability of an arbitrary formula over Boolean literals is NP-complete.
- Clique: Determining the existence of a clique (= a complete subgraph) of a given size in a graph is NP-complete.
- Vertex Cover: Determining the existence of a vertex cover (a vertex subset incident to all edges) of a given size in a graph is NP-complete.
- Subset Sum: Determining the existence of a subset, of a given set, that has a given sum is NP-complete.

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Pseudo-Polynomial Algorithms

Example (Subset Sum)

Determining the existence of a subset, of a given set S of n numbers, that has a given sum t is NP-complete:

- A dynamic-programming algorithm takes O(n · t) time, as each entry in its n × t table can be computed in O(1) time.
- This is polynomial in the given size *n* of *S* and polynomial in the magnitude of the input *t*, which can be large depending on *n* and the numbers in *S*.
- This is exponential in the size $\lceil \log_b t \rceil$ of the base-*b* representation of *t*, since $t = b^{\log_b t}$ (usually: b = 2).

Definition

An algorithm of complexity polynomial in the magnitude of its input numbers is said to be pseudo-polynomial.

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NP Completeness: Proof by Reduction

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Relationships What Now? Proving that a problem *R* of NP is NP-complete can be done by showing that $E \leq_P R$ for some existing NP-complete problem *E*, since by definition $Q \leq_P E$ for every problem *Q* in NP. If a polynomial-time algorithm for *R* existed, then we would have a polynomial-time algorithm for *E*, which would lead to P = NP.

Examples (exercises will be given in the AD3 course)

- SAT is NP-complete (Cook, 1971; Levin, 1973).
- SAT reduces to 3-SAT, but not to 2-SAT.
- 3-SAT reduces to Clique and to Subset Sum.
- Clique reduces to Vertex Cover, which reduces to Hamiltonian Cycle, which reduces to Travelling Salesperson (TSP), asking if there is a Hamiltonian cycle with cost at most k in a complete weighted graph.



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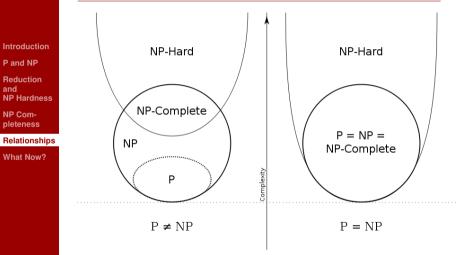
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Remarks

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- If P ≠ NP, then there exist problems in NP that are neither in P nor NP-complete. Artificial such problems can be constructed, but integer factorisation and graph isomorphism are practical problems in NP that are currently not known to be in P and not known to be NP-complete.
- There exist many other complexity classes, chartering the territory outside NP, some of them overlapping with the NP-hard class, and containing practical problems, such as planning. Determining a precise complexity map is contingent upon settling the P versus NP question.
- The stable matching problem is believed by many to be hard, but it can be solved in O(n) time for n hospitals and n students, and is thus in P (Gale and Shapley, 1962). Shapley shared the Nobel Prize in Economics 2012.



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In a satisfaction problem, a 'yes' answer includes a witness. In an optimisation problem, a 'yes' answer includes an optimal witness according to some cost function.

Satisfaction and optimisation problems with NP-complete decision problems are often also said to be NP-hard.

(Recall the method on slide 11 for finding a longest path.)

Several courses at Uppsala University teach techniques for addressing NP-hard optimisation or satisfaction problems:

Algorithms and Datastructures 3 (1DL481) (period 3)

(period 2)

(period 1)

- Continuous Optimisation (1TD184)
- Modelling for Combinatorial Optimisation (1DL451)
- Comb'l Optimisation & Constraint Programming (1DL442) (periods 1+2)

INP completeness is not where the fun ends, but where the fun begins!