# Chapter 34: P versus NP, A Gentle Introduction (Version of 14th December 2023) 

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Course 1DL231:
Algorithms and Data Structures 2 (AD2)

## Outline

1. Introduction
2. P and NP
3. Reduction and NP Hardness
4. NP Completeness
5. Relationships
6. What Now?

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## 1. Introduction

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This is one of the seven Millennium Prize problems of the Clay Mathematics Institute (Massachusetts, USA), each worth 1 million US\$.

Informally:
■ P = class of problems that need no search in order to be solved NP = class of problems that might need search in order to be solved
■ $\mathrm{P}=$ class of problems with easy-to-compute solutions NP = class of problems with easy-to-check solutions
Thus: Can search always be avoided ( $\mathrm{P}=\mathrm{NP}$ ), or is search sometimes necessary ( $P \neq N P$ )?

Computational tasks that are doable in polynomial time (in the input size) are said to be tractable or easy.
Tasks requiring non-polynomial time are said to be intractable or hard.

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## P and NP: Definitions and Examples

A bit more formally, and focussing on decision problems for NP, whose answer is 'yes' or 'no', for inputs of size $n$ :

■ $P=$ the class of easy problems, whose solutions can be computed in polynomial time: $\mathcal{O}\left(n^{k}\right)$ time for some fixed $k$.
Examples: sorting; almost all problems in this course.
■ NP = the class of problems where a witness can be checked in polynomial time when the answer is 'yes'. NP stands not for "non-polynomial time", but for "non-deterministic polynomial time". We trivially have $\mathrm{P} \subseteq$ NP.
Example: Given an n-digit number, does it have a divisor ending in 7 ? Computing such a divisor seems hard, but checking a witness, that is a candidate divisor, is easy.
■ Undecidable problems cannot be solved by any algorithm, no matter how much time is allocated. Examples: halting problem; disjointness of CFLs. So not all problems are in NP, independently of $P$ versus NP.

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## $P$ and NP

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Informally:

■ A problem $Q$ reduces to a problem $R$, denoted $Q \leq_{p} R$, if every instance of $Q$ can be transformed in polynomial time into an instance of $R$ that has the same yes/no answer. We also say that $R$ is at least as hard as $Q$. Note that $\leq_{\mathrm{p}}$ is transitive: $\forall Q, E, R: Q \leq_{\mathrm{p}} E \leq_{\mathrm{p}} R \Rightarrow Q \leq_{\mathrm{p}} R$.

■ Proving that a problem $Q$ is in P can be done by showing that $Q \leq_{\mathrm{P}} E$ for some existing problem $E$ in P .

■ A problem is NP-hard if it is at least as hard as every problem in NP: we have that every problem in NP reduces to an NP-hard problem.

■ On slide 19 is a wider definition of NP hardness.

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## (Cook, 1971; Levin, 1973)

Formally:
■ A problem is NP-complete if it is in NP and is NP-hard.
If some NP-complete problem is polynomial-time solvable, then every problem in NP is polynomial-time solvable: $P \supseteq N P$ and so $P=N P$.
An NP-complete problem is polynomial-time solvable if and only if $P=N P$. If some problem in NP is not polynomial-time solvable ( $\mathrm{P} \neq \mathrm{NP}$ ), then no NP-complete problem is polynomial-time solvable.
The status of NP-complete problems is currently unknown: No polynomial-time algorithm was found for any of them, and no proof was made that no such algorithm can exist.
Most experts believe NP-complete problems are intractable, as the opposite would be truly amazing.

## NP Completeness: Examples

Given a digraph $(V, E)$ and two vertices $u, v \in V$ :

## Examples

- Finding a shortest path from $u$ to $v$ takes $\mathcal{O}(V \cdot E)$ time and is thus in P .

■ Determining the existence of a simple path (which has distinct vertices) that has at least a given number $\ell$ of edges is NP-complete. Hence finding a longest path seems hard: increase $\ell$ starting from a trivial lower bound, until the answer is ' no '.

## Examples

■ Finding an Euler tour (which visits each edge once) takes $\mathcal{O}(E)$ time and is thus in P .

- Determining the existence of a Hamiltonian cycle (which visits each vertex once) is NP-complete.


## NP Completeness: More Examples

## Examples

- 2-SAT: Determining the satisfiability of a conjunction of disjunctions of 2 Boolean literals is in P .

■ 3-SAT: Determining the satisfiability of a conjunction of disjunctions of 3 Boolean literals is NP-complete.
■ SAT: Determining the satisfiability of an arbitrary formula over Boolean literals is NP-complete.
■ Clique: Determining the existence of a clique (= a complete subgraph) of a given size in a graph is NP-complete.
■ Vertex Cover: Determining the existence of a vertex cover (a vertex subset incident to all edges) of a given size in a graph is NP-complete.
■ Subset Sum: Determining the existence of a subset, of a given set, that has a given sum is NP-complete.

## Pseudo-Polynomial Algorithms

## Example (Subset Sum)

Determining the existence of a subset, of a given set $S$ of $n$ numbers, that has a given sum $t$ is NP-complete:

- A dynamic-programming algorithm takes $\mathcal{O}(n \cdot t)$ time, as each entry in its $n \times t$ table can be computed in $\mathcal{O}(1)$ time.
- This is polynomial in the given size $n$ of $S$ and polynomial in the magnitude of the input $t$, which can be large depending on $n$ and the numbers in $S$.
■ This is exponential in the size $\left\lceil\log _{b} t\right\rceil$ of the base- $b$ representation of $t$, since $t=b^{\log _{b} t}$ (usually: $b=2$ ).


## Definition

An algorithm of complexity polynomial in the magnitude of its input numbers is said to be pseudo-polynomial.

## NP Completeness: Proof by Reduction

Proving that a problem $R$ of NP is NP-complete can be done by showing that $E s_{\mathrm{p}} R$ for some existing NP-complete problem $E$, since by definition $Q \leq_{\mathrm{p}} E$ for every problem $Q$ in NP. If a polynomial-time algorithm for $R$ existed, then we would have a polynomial-time algorithm for $E$, which would lead to $P=N P$.

## Examples (exercises will be given in the AD3 course)

$■$ SAT is NP-complete (Cook, 1971; Levin, 1973).
■ SAT reduces to 3-SAT, but not to 2-SAT.
■ 3-SAT reduces to Clique and to Subset Sum.

- Clique reduces to Vertex Cover, which reduces to Hamiltonian Cycle, which reduces to Travelling Salesperson (TSP), asking if there is a Hamiltonian cycle with cost at most $k$ in a complete weighted graph.


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■ If $P \neq N P$, then there exist problems in NP that are neither in $P$ nor NP-complete. Artificial such problems can be constructed, but integer factorisation and graph isomorphism are practical problems in NP that are currently not known to be in P and not known to be NP-complete.

■ There exist many other complexity classes, chartering the territory outside NP, some of them overlapping with the NP-hard class, and containing practical problems, such as planning. Determining a precise complexity map is contingent upon settling the $P$ versus NP question.

■ The stable matching problem is believed by many to be hard, but it can be solved in $\mathcal{O}(n)$ time for $n$ hospitals and $n$ students, and is thus in P (Gale and Shapley, 1962). Shapley shared the Nobel Prize in Economics 2012.

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## What Now?

In a satisfaction problem, a 'yes' answer includes a witness.
In an optimisation problem, a 'yes' answer includes an optimal witness according to some cost function.
Satisfaction and optimisation problems with NP-complete decision problems are often also said to be NP-hard.
(Recall the method on slide 11 for finding a longest path.)
Several courses at Uppsala University teach techniques for addressing NP-hard optimisation or satisfaction problems:

■ Algorithms and Datastructures 3 (1DL481) (period 3)

- Continuous Optimisation (1TD184) (period 2)
■ Modelling for Combinatorial Optimisation (1DL451)
- Comb'l Optimisation \& Constraint Programming (1DL442) (periods 1+2) NP completeness is not where the fun ends, but where the fun begins!

