# Chapter 34: P versus NP, A Gentle Introduction 

 (Version of 18th December 2022)Pierre Flener

Department of Information Technology
Computing Science Division
Uppsala University
Sweden

Course 1DL231:
Algorithms and Data Structures 2 (AD2)

## Outline

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Problems that are solvable in polynomial time (in the input size) are considered tractable, or easy. Problems requiring non-polynomial time are considered intractable, or hard.

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## P and NP: Definitions and Examples

A bit more formally, and focussing on decision problems for NP, whose answer is 'yes' or 'no', for inputs of size $n$ :

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■ Undecidable problems cannot be solved by any algorithm, no matter how much time is allocated. Examples: halting problem; disjointness of two CFLs. So not all problems are in NP, independently of $P$ versus NP.

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## Reduction and NP Hardness

## (Karp, 1972)

Informally:

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■ On slide 19 is a wider definition of NP hardness.

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## NP Completeness (Cook, 1971; Levin, 1973)

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Most experts believe NP-complete problems are intractable, as the opposite would be truly amazing.

## NP Completeness: Examples

Given a digraph $(V, E)$ :

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- Determining the existence of a Hamiltonian cycle (which visits each vertex once) is NP-complete.


## NP Completeness: More Examples

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- Vertex Cover: Determining the existence of a vertex cover (a vertex subset with at least one endpoint for all edges) of a given size in a graph is NP-complete.
■ Subset Sum: Determining the existence of a subset, of a given set, that has a given sum is NP-complete.

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## Pseudo-Polynomial Algorithms

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■ This is exponential in the size $\left\lceil\log _{b} t\right\rceil$ of the base- $b$ representation of $t$, since $t=b^{\log _{b} t}$ (usually: $b=2$ ).


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## Definition

An algorithm of complexity polynomial in the magnitude of its input numbers is said to be pseudo-polynomial.

## NP Completeness: Proof by Reduction

Proving that a problem $R$ of NP is NP-complete is doable by showing $E \leq_{\mathrm{p}} R$ for some existing NP-complete problem $E$, since by definition $Q \leq_{\mathrm{p}} E$ for every problem $Q$ in NP.

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- 3-SAT reduces to Clique and Subset Sum.
- Clique reduces to Vertex Cover, which reduces to Hamiltonian Cycle, which reduces to Travelling Salesperson (TSP), asking if there is a Hamiltonian cycle with cost at most $k$ in a complete weighted graph.


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Reduction

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$P \neq N P$


$$
P=N P
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## Remarks

■ If $P \neq N P$, then there exist problems in NP that are neither in P nor NP-complete. Artificial such problems can be constructed, but integer factorisation and graph isomorphism are practical problems in NP that are currently not known to be in P or to be NP-complete.
■ There exist many other complexity classes, chartering the territory outside NP, some of them overlapping with the NP-hard class, and containing practical problems, such as planning. Determining a precise complexity map is contingent upon settling the P versus NP issue.

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■ There exist many other complexity classes, chartering the territory outside NP, some of them overlapping with the NP-hard class, and containing practical problems, such as planning. Determining a precise complexity map is contingent upon settling the $P$ versus NP issue.
■ The stable matching problem is believed by many to be hard, but it can be solved in $\mathcal{O}(n)$ time for $n$ hospitals \& $n$ students, and is thus in P (Gale and Shapley, 1962). Shapley shared the Nobel Prize in Economics 2012.

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## What Now?

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In a satisfaction problem, a 'yes' answer includes a witness. In an optimisation problem, a 'yes' answer includes an optimal witness according to some cost function. Satisfaction and optimisation problems with NP-complete decision problems are often also said to be NP-hard. (Recall the method on slide 11 for finding a longest path.)
Several courses at Uppsala University teach techniques for addressing NP-hard optimisation or satisfaction problems:

■ Algorithms and Datastructures 3 (1DL481) (period 3)
■ Continuous Optimisation (1TD184) (period 2)
■ Modelling for Combinatorial Optim. (1DL451) (period 1)
■ CO \& Constraint Programming (1DL442) (periods 1+2) NP completeness is where the fun begins (not ends)!

