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# A discontinuous Galerkin local orthogonal decomposition method for elliptic multiscale problems

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## Model problem

Consider the convection-diffusion problem

$$\begin{aligned} -\nabla \cdot A \nabla u + \mathbf{b} \cdot \nabla u &= f \text{ in } \Omega, \\ u &= 0 \text{ on } \partial\Omega. \end{aligned}$$

where

- $0 < A_{min} \in \mathbb{R} \leq A(x) \in L^\infty(\Omega, \mathbb{R}_{sym}^{d \times d})$ ,
- $f \in L^2(\Omega)$ ,
- $\mathbf{b} \in [W_\infty^1(\Omega)]^d$ , and  $\nabla \cdot \mathbf{b} = 0$ .

## Discontinuous Galerkin discretization

- $a_h(\cdot, \cdot)$ : symmetric interior penalty (SIPG) and upwind.
- The energy-norm is defined by

$$\|[\![ \cdot ]\!] \|_H^2 = \|A^{1/2} \nabla_H \cdot \|_{L^2(\Omega)}^2 + \sum_{e \in \mathcal{E}} \left( \frac{\sigma}{H} + \frac{|\mathbf{b} \cdot \nu|}{2} \right) \|[\![ \cdot ]\!] \|_{L^2(e)}^2$$

- Let  $\mathcal{V}_H$  be the space of discontinuous piecewise (bi)linear polynomials.

### (One scale) DG method

Find  $u_H \in \mathcal{V}_H$  such that

$$a_H(u_H, v) = F(v), \quad \text{for all } v \in \mathcal{V}_H.$$

## (One scale) DG method ( $\mathbf{b} = 0$ )

Find  $u_H \in \mathcal{V}_H$  such that

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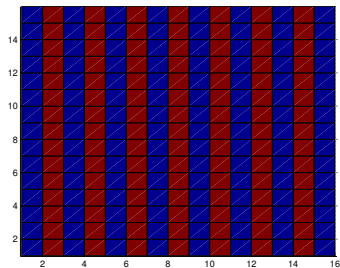


Figure : The coefficient  $A$  in the model problem.

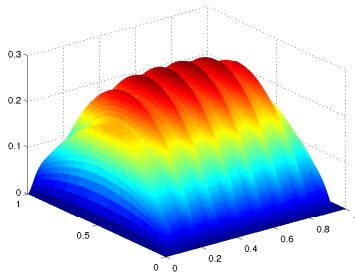


Figure : Reference solution.

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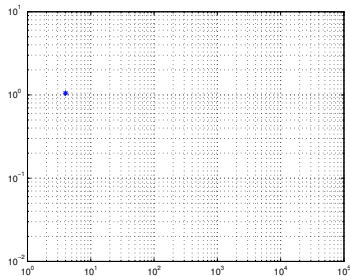


Figure : Energy norm with respect to the degrees of freedom.

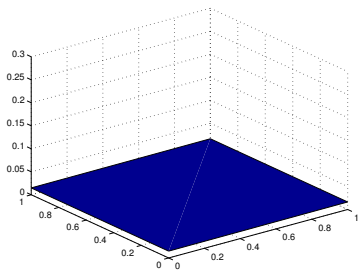


Figure : Solution obtained using the discontinuous Galerkin method.

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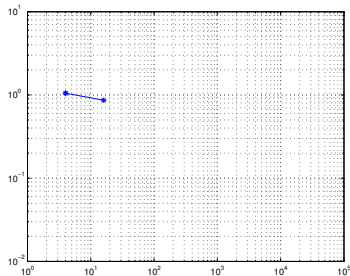


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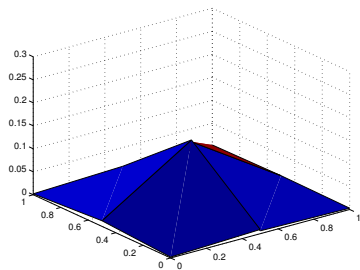


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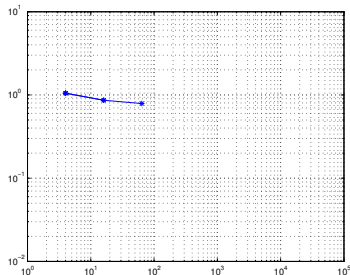


Figure : Energy norm with respect to the degrees of freedom.

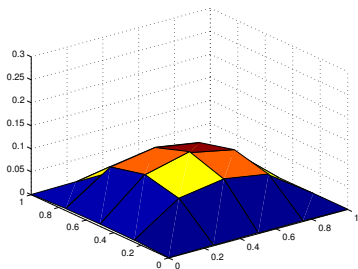


Figure : Solution obtained using the discontinuous Galerkin method.

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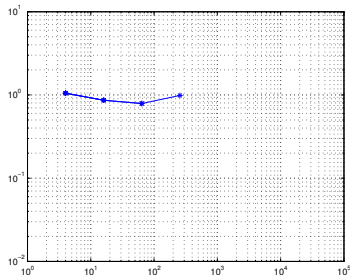


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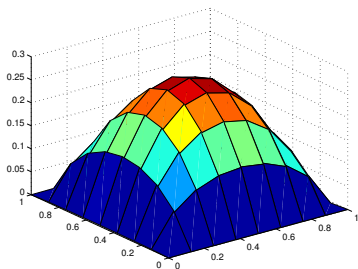


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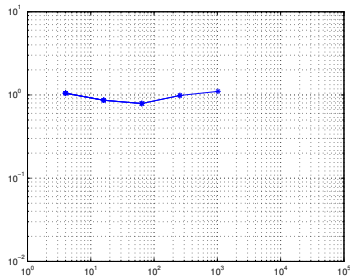


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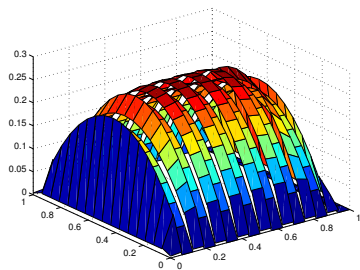


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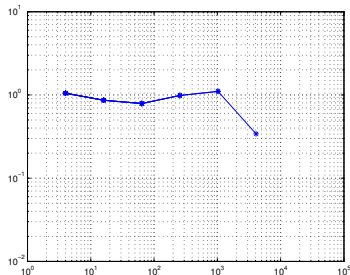


Figure : Energy norm with respect to the degrees of freedom.

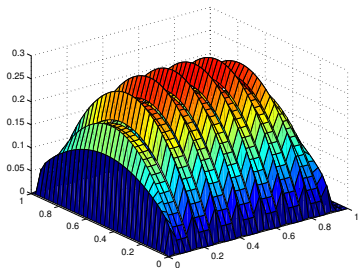


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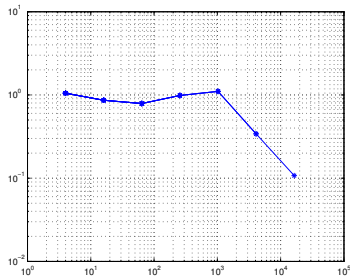


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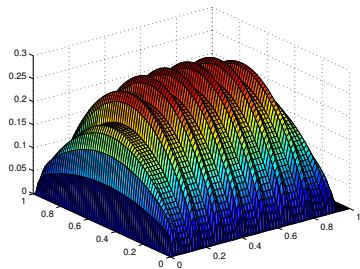


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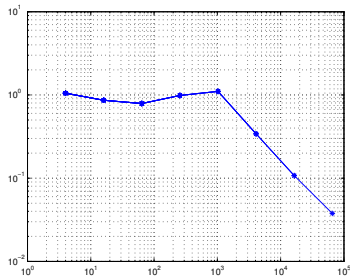


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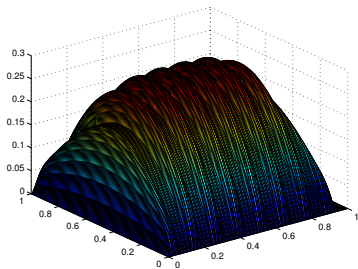


Figure : Solution obtained using the discontinuous Galerkin method.

## Multiscale split

- Consider  $\mathcal{V}_H$  and  $\mathcal{V}_h$ , such that  $\mathcal{V}_H \subset \mathcal{V}_h$ .
- Let  $\Pi_H$  be the  $L^2$ -projection onto  $\mathcal{V}_H$ .
- Define  $\mathcal{V}^f(\omega) = \{v \in \mathcal{V}_h(\omega) : \Pi_H v = 0\}$ .
- We have a  $L^2$ -orthogonal split;  $\mathcal{V}_h = \mathcal{V}_H \oplus \mathcal{V}^f$ .

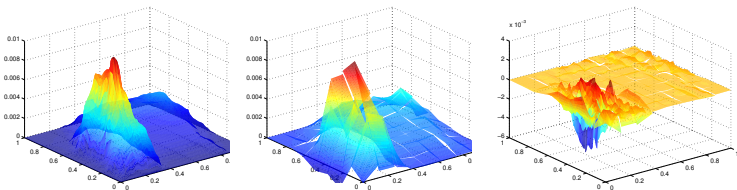


Figure :  $u_h = u_H + u^f$

## Corrected basis functions

- For each  $\lambda_{T,j} \in \mathcal{V}_H$  we compute a corrector, find  $\phi_{T,j}^L \in \mathcal{V}^f(\omega_T^L)$  such that

$$a_h(\phi_{T,j}^L, v_f) = a_h(\lambda_{T,j}, v_f), \quad \text{for all } v_f \in \mathcal{V}^f(\omega_T^L).$$

where  $L$  indicates the size of the patch.

- Corrected space:  $\mathcal{V}_H^{ms} = \text{span}\{\lambda_{T,j} - \phi_{T,j}^L\}$ .
- We have a  $a(\cdot, \cdot)$ -orthogonal split;  $\mathcal{V}_h = \mathcal{V}_H^{ms} \oplus \mathcal{V}^f$ .

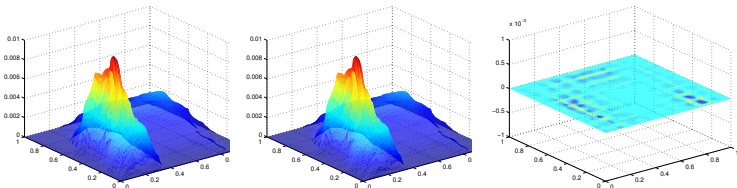
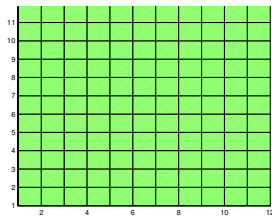
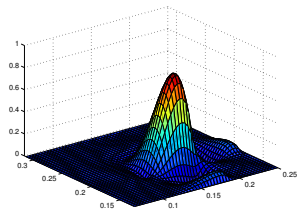
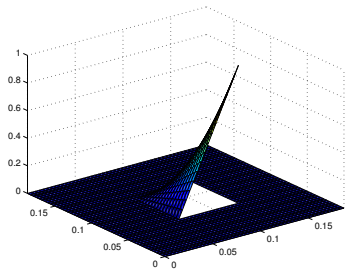
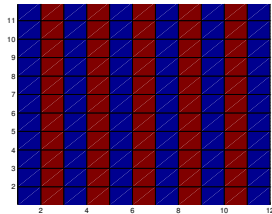
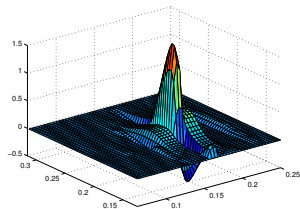
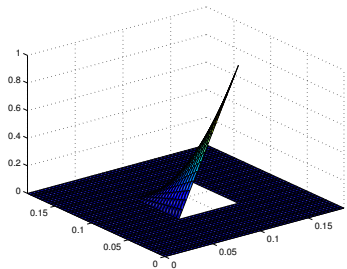


Figure :  $u_h = u_H^{ms} + u^f$

## Examples of corrected basis functions

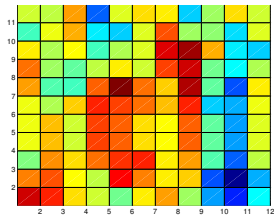
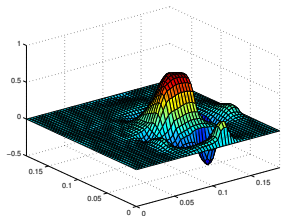
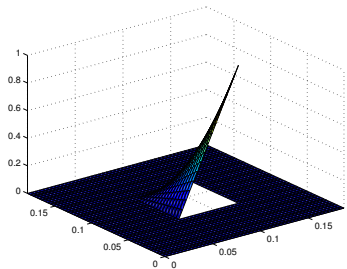


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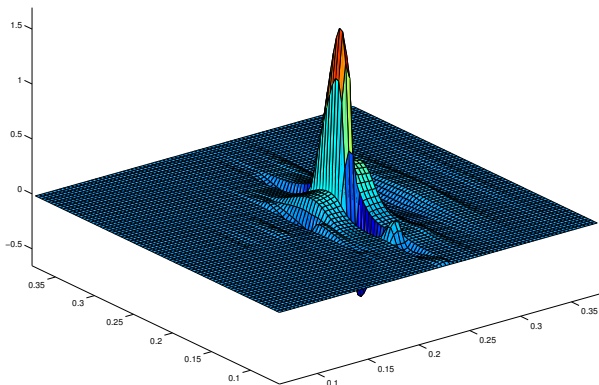


## Examples of corrected basis functions



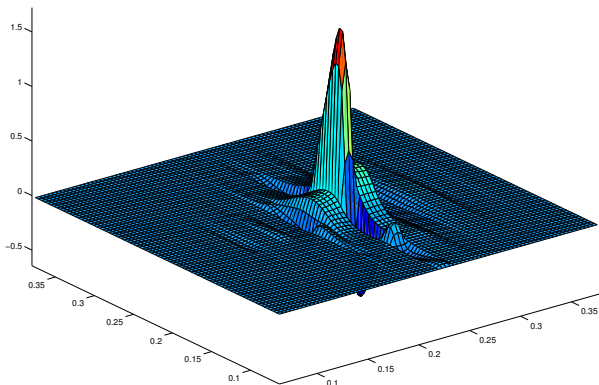
## Example of corrected basis function

- With  $\mathbf{b} = [0, 0]'$ .



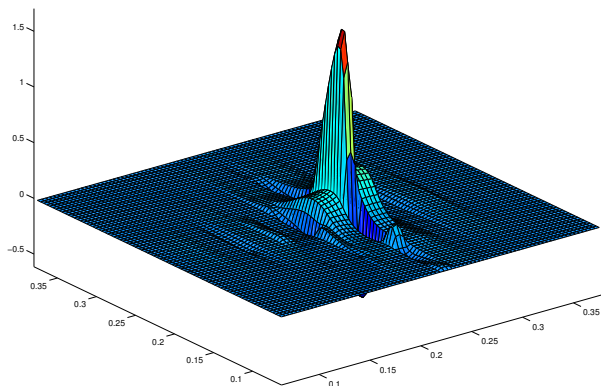
## Example of corrected basis function

- With  $\mathbf{b} = -[1, 0]'$ .



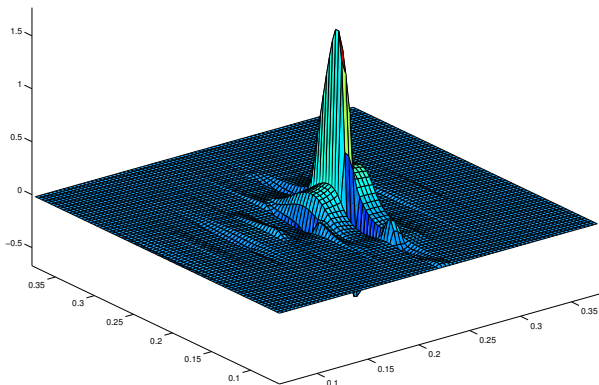
## Example of corrected basis function

- With  $\mathbf{b} = -[2, 0]'$ .



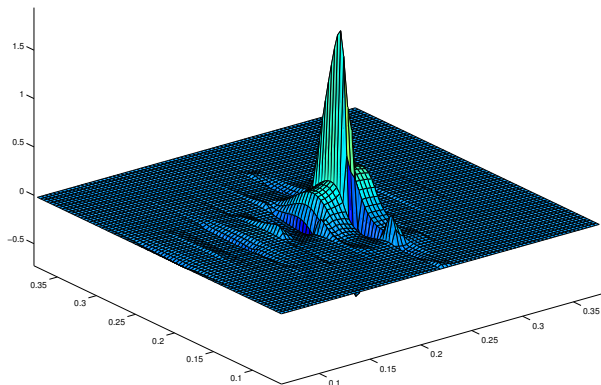
## Example of corrected basis function

- With  $\mathbf{b} = -[4, 0]'$ .



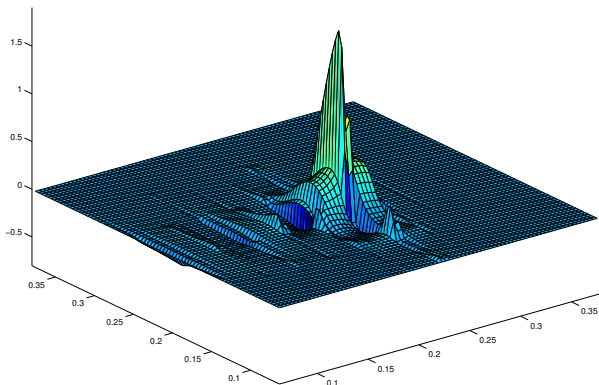
## Example of corrected basis function

- With  $\mathbf{b} = -[8, 0]'$ .



## Example of corrected basis function

- With  $\mathbf{b} = -[16, 0]'$ .



## Discontinuous Galerkin multiscale method

Consider the problem: find  $u_H^{ms,L} \in \mathcal{V}_L^{ms} = \text{span}\{\lambda_{T,j} - \phi_{T,j}^L\}$  such that

$$a_h(u_H^{ms,L}, v) = F(v), \quad \text{for all } v \in \mathcal{V}_H^{ms,L}.$$

- $\dim \mathcal{V}_H^{ms,L} = \dim \mathcal{V}_H$
- The basis function are solved independently of each other.
- Method can take advantage of periodicity.



## A priori error bound

Under the assumption  $\mathcal{O}(\|H\mathbf{b}\|_{L^\infty(\Omega)}/A_{min}) = 1$  it holds:

### Lemma (Decay of corrected basisfunctions)

For  $\phi_{T,j} \in \mathcal{V}^f(\omega_i^L)$ , there exist  $a$ ,  $0 < \gamma < 1$ , such that

$$\|\phi_{T,j} - \phi_{T,j}^L\| \lesssim \gamma^L \|\lambda_j - \phi_{T,j}\|.$$

### Theorem

For  $u_H^{ms,L} \in \mathcal{V}_H^{ms,L}$ , there exist  $a$ ,  $0 < \gamma < 1$ , such that

$$\|u - u_H^{ms,L}\| \lesssim \|u - u_h\| + \|H(f - \Pi_H f)\|_{L^2} + H^{-1}(L)^{d/2} \gamma^L \|f\|_{L^2}.$$

Choosing  $L = \lceil C \log(H^{-1}) \rceil$  both terms behave in the same manor with an appropriate  $C$ .

## Numerical verification of the convergence

$$-\nabla \cdot A \nabla u + \mathbf{b} \cdot \nabla u = f \text{ in } \Omega,$$

$$u = 0 \text{ on } \partial\Omega.$$

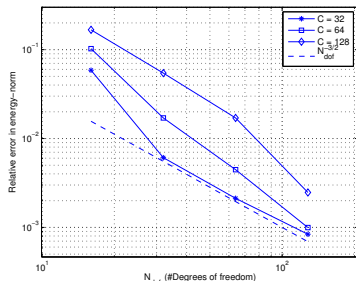


Figure : #dofs vs  
 $\| |u_h - u_{H,L}^{ms} | \| / \| |u_h | \|$

- Let  $A = 1$  and  $\mathbf{b} = C[1, 0]'$  for  $C = 32, 54, 128$ .
- Choose  $L = \lceil 2 \log(\frac{1}{H}) \rceil$ .
- Let the right hand side be:  
 $f = 1 + \sin(\pi x) + \sin(\pi y)$ .
- Let  $H = 2^{-m}$  for  
 $m = \{2, 3, 4, 5\}$ .
- Reference mesh is  $2^{-7}$ .

$$-\nabla \cdot A \nabla u + \mathbf{b} \cdot \nabla u = f \text{ in } \Omega,$$

$$u = 0 \text{ on } \partial\Omega.$$

- Let  $\mathbf{b} = [1, 0]'$ .

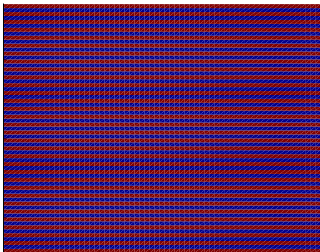


Figure : Diffusion coefficient  $A$ ,  
 $A_{max}/A_{min} = 100$  and  $A_{min} = 0.01$ .

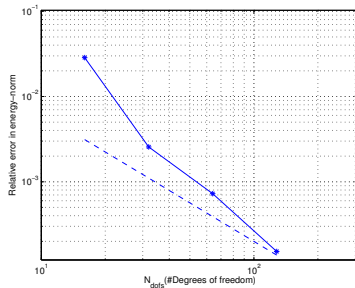


Figure : #dofs vs  
 $|||u_h - u_{H,L}^{ms}||| / |||u_h|||$

$$-\nabla \cdot A \nabla u + \mathbf{b} \cdot \nabla u = f \text{ in } \Omega,$$

$$u = 0 \text{ on } \partial\Omega.$$

- Let  $\mathbf{b} = [512, 0]'$ .

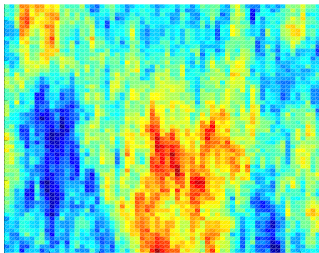


Figure : Diffusion coefficient  $A$  with  $A_{max}/A_{min} \sim 10^5$  and  $A_{min} = 0.05$ .

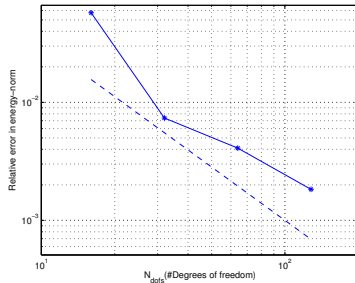


Figure : #dofs vs  $\|u_h - u_{H,L}^{ms}\| / \|u_h\|$

## Adaptivity and a posteriori error bound ( $\mathbf{b} = 0$ )

### Theorem (A posteriori error bound)

Let  $u_H^{ms,L}$  be the multiscale solution, then

$$\| \| u - u_H^{ms,L} \| \| \lesssim \left( \sum_{T \in \mathcal{T}_H} \rho_{h,T}^2(u_H^{ms,L}) \right)^{1/2} + \left( \sum_{T \in \mathcal{T}_H} \rho_{L,\omega_T^L}^2(u_H^{ms,L}) \right)^{1/2}.$$

- $\rho_{L,\omega_T^L}^2$  measures the effect of the truncated patches.
- $\rho_{h,T}^2$  measures the effect of the refinement level.

- We consider the permeabilities

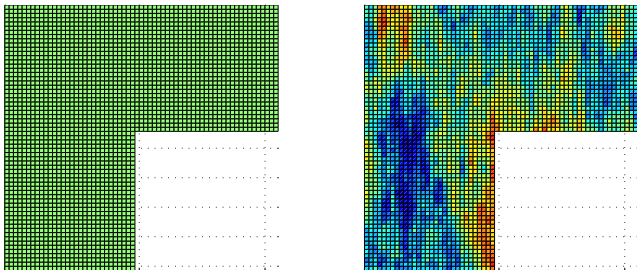


Figure : Permeabilities *One* left and *SPE* right.

- Using a refinement level of 30% we have.

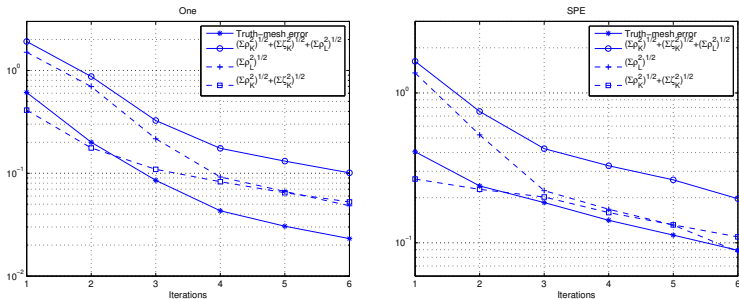
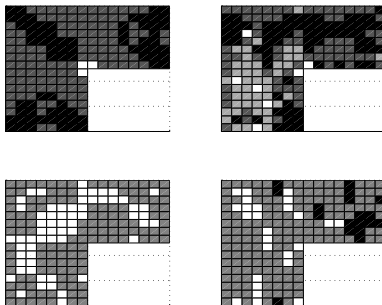


Figure : Convergence plot for *One* left and *SPE* right.



**Figure :** One (left) and SPE (right). The level of refinement (upper) and size of the patches (lower).



## Perspective towards Two-Phase flow

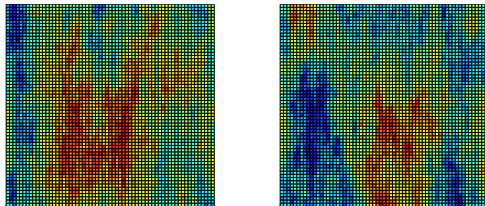
Buckley-Leverett system

$$-\nabla \cdot (K\lambda(S)\nabla p) = q \text{ and } \partial_t S + \nabla \cdot (f(s)\mathbf{v}) = q_w$$

is solved using IMPES. Here

- $K$  is the hydraulic conductivity,
- $\lambda(S)$  is the total mobility (essentially macroscopic),
- and  $\mathbf{v} = -K\lambda(S)\nabla p$  is obtained from the pressure equation.

- Coarse mesh  $H = 2^{-5}$  and fine mesh  $h = 2^{-8}$ .
- Boundary condition  $p = 1$ , on left boundary  $p = 0$  on right boundary, and  $K\lambda(S)\nabla p = 0$  otherwise.
- Preprocessing step: compute the basis corrected basis using  $\lambda(S) = 1$



**Figure :**  $K_1$  ( $A_{max}/A_{min} \approx 5 \cdot 10^5$ ) left and  $K_2$  ( $A_{max}/A_{min} \approx 4 \cdot 10^5$ ) right on a mesh with size  $2^{-6}$ .

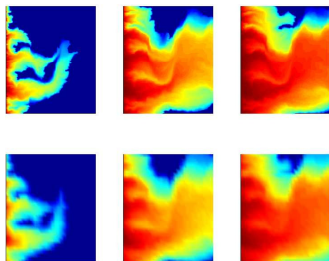


Figure : Saturation profile  $K_1$  for  $T_1$ ,  $T_2$ , and  $T_3$ .

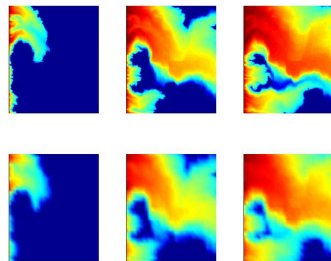






Figure : Saturation profile  $K_2$  for  $T_1$ ,  $T_2$ , and  $T_3$ .

Data	$\ e(T_1)\ _{L^2(\Omega)}$	$\ e(T_2)\ _{L^2(\Omega)}$	$\ e(T_3)\ _{L^2(\Omega)}$
1	0.088	0.073	0.070
2	0.058	0.087	0.079

Table : Error in relative  $L^2$ -norm,  $e(T) = S(T) - S^{\text{ref}}(T)$ .

-  **D. ELFVERSON, G. H. GEORGOULIS, AND A. MÅLQVIST**  
An adaptive discontinuous Galerkin multiscale method for elliptic problems. *Multiscale Model. Simul.*
  -  **D. ELFVERSON, G. H. GEORGOULIS, A. MÅLQVIST AND D. PETERSEIM**  
Convergence of discontinuous Galerkin multiscale methods. *SIAM J. Numer. Anal.*
  -  **D. ELFVERSON**  
A discontinuous Galerkin multiscale method for convection-diffusion problems. *Submitted.*
  -  **D. ELFVERSON, V. GINTING, P. HENNING**  
On Multiscale Methods in Petrov-Galerkin formulation.  
*arXiv:1405.5758, submitted.*
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