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Uncertainty Quantification for Multiscale Problems

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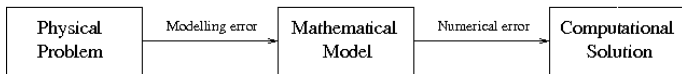
Short CV

- PhD in applied mathematics,
Chalmers, 2005, adviser Mats G. Larson
- postdoc, applied mathematics, joint between
Colorado State University, 2005-2006
University of California at San Diego, 2006-2007
- assistant professor (biträdande lektor), numerical
analysis, Uppsala University, 2007-present



Uncertainty Quantification (UQ)

Decisions are very often based on computer simulations. Quantification of the effect of uncertainties in the simulations is therefore crucial.

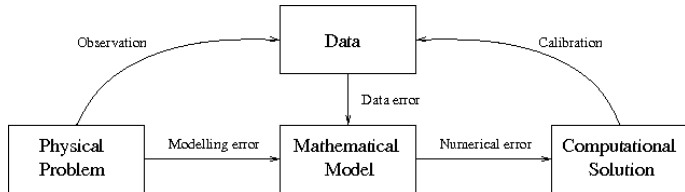


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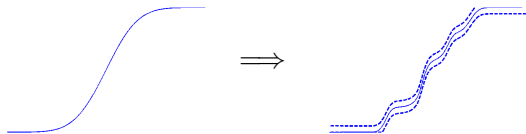
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Example: Climate prediction



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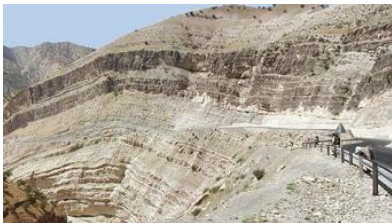
- ▶ We need to control the error in the QoI.
- ▶ A probabilistic representation of the data is used to model uncertainty.
- ▶ The QoI becomes a random variable, whose distribution is often unknown, non-parametric density estimation is needed.



A cumulative distribution function (cdf) of the data gives an approximate cdf of the QoI.



Example: Secondary oil recovery



Water is injected to move oil to producing well.

$$\dot{s} + \nabla \cdot [f(s)v] = g, \quad \nabla \cdot v = q, \quad v = -\lambda(s)k\nabla p$$

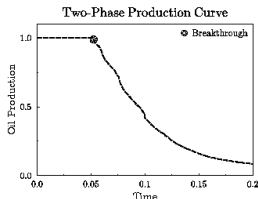
s is water conc. p is pressure, and k is permeability.

- ▶ QoI is the time it takes for the water to reach the producing well (breakthrough time t^*).
- ▶ There is uncertainty in k due to very sparse and possibly inaccurate measurements.
- ▶ Modeling error due to simplified model.



Analysis of numerical and statistical error

Probabilistic representation of $k \Rightarrow t^*$ is random variable with cdf $F(x) = P(t^* < x)$.



We compute samples \tilde{t}^* numerically and use MC (n samples) to get $\tilde{F}(x)$. With probability p it holds:

$$|F(x) - \tilde{F}(x)| \leq \frac{c(p)}{\sqrt{n}} + \tilde{F}(x + \varepsilon) - \tilde{F}(x - \varepsilon)$$

where $|t^* - \tilde{t}^*| \leq \varepsilon$ (goal oriented error estimation techniques). Can be used in adaptive algorithm!

(N9) Estep, Målqvist, Tavener, SIAM J. Sci. Comp., 31 (2009) 2935–2959.

(N43) Ginting, Målqvist, Presho, SIAM MMS, 8 (2010) 977–996.

Presho, Målqvist, Ginting, Adv. Water Res. 33 (2010) 1130–1141.



Conclusions

- Error analysis and quantification of uncertainty will become more important as the computer development allows us to study increasingly complex problems.
- The simple example of the error bound clearly indicates the need for a new type of error estimators.
- Numerical algorithms have previously been optimized for solving complex problems once (or a few times). UQ calls for algorithms that are optimal for solving a vast number of similar problems.